

The structural evolution of temporal hypergraphs through the lens of hyper-cores

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ABSTRACT

The richness of many complex systems stems from the interactions among their components. The higher-order nature of these interactions, involving many units at once, and their temporal dynamics constitute crucial properties that shape the behaviour of the system itself. An adequate description of these systems is offered by temporal hypergraphs, that integrate these features within the same framework. However, tools for their temporal and topological characterization are still scarce. Here we develop a series of methods specifically designed to analyse the structural properties of temporal hypergraphs at multiple scales. Leveraging the hyper-core decomposition of hypergraphs, we follow the evolution of the hyper-cores through time, characterizing the hypergraph structure and its temporal dynamics at different topological scales, and quantifying the multi-scale structural stability of the system. We also define two static hypercoreness centrality measures that provide an overall description of the nodes aggregated structural behaviour. We apply the characterization methods to several data sets, establishing connections between structural properties and specific activities within the systems. Finally, we show how the proposed method can be used as a model-validation tool for synthetic temporal hypergraphs, distinguishing the higher-order structures and dynamics generated by different models from the empirical ones, and thus identifying the essential model mechanisms to reproduce the empirical hypergraph structure and evolution. Our work opens several research directions, from the understanding of dynamic processes on temporal higher-order networks to the design of new models of time-varying hypergraphs.

Keywords: Temporal hypergraphs; Hyper-core decomposition; Temporal-topological characterization; Multi-scale structural stability; Model validation.

I. INTRODUCTION

Many complex systems composed of interacting elements can be effectively described within the theory of static networks [1–3]. This powerful framework provides a wide set of techniques and tools to characterize the interactions at different topological scales, through global graph properties (e.g. density), possibly focusing on specific groups of relevant nodes (e.g. k -cores) and providing various measures of node centralities. Furthermore, this multi-scale characterization helps identify nodes and mesostructures with relevant roles in dynamical processes, since the interaction structure deeply impacts processes unfolding on networks [3, 4]. Despite the power of network theory, recently several empirical evidences have brought out the limits of this framework, which by definition is restricted to a static description of systems involving only binary interactions.

On the one hand, several systems present time-varying interactions, which follow specific dynamics and temporal patterns [5–7]: for example, human social interactions [8], scientific collaborations [9] and neural systems [5, 10]. These systems are represented using *temporal networks*, a generalization of static networks in which nodes interact

via links with specific activation and deactivation times [5, 6]. Several structural characterization tools for static networks have been generalized to time-varying graphs, showing the non-trivialities emerging from the introduction of the temporal dimension [5–7]: for instance, span-cores can decompose a temporal graph into subgraphs of controlled duration and increasing connectivity [11, 12]. Moreover, dynamic processes on temporal networks are also impacted by the network dynamics, especially when the dynamics of and on the network have comparable time scales [5, 6, 13, 14].

On the other hand, many complex systems also feature interactions between groups of agents, not reducible to sets of pairs [15, 16]: this is the case for example of human social interactions [17], scientific collaborations [18] and species interactions in ecosystems [19]. An adequate description of these systems involves *hypergraphs*, a generalization of networks in which nodes can interact in groups of arbitrary size, i.e., hyperedges [15]. Taking into account such higher-order nature of interactions leads to the definition of new structures and concepts and to new dynamical phenomena [15, 16, 20–22]. Indeed, several dynamical processes, including contagion dynamics, synchronization phenomena and consensus formation, exhibit richer and more complex dynamics when defined on higher-order networks, with important differences with respect to the dynamics occurring on pair-

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80 wise networks, such as changes in the nature of the phase
81 transitions observed [15, 20, 21, 23]. Despite the rele-
82 vance of such higher-order effects, tools to characterize
83 hypergraphs at various scales have only recently been pro-
84 posed: for example, efforts have been devoted to defin-
85 ing explicitly higher-order centrality measures, account-
86 ing for information otherwise impossible to retrieve by
87 pairwise measures [15, 24]; moreover, a few techniques
88 and methods have been developed to identify relevant
89 higher-order substructures in hypergraphs [15, 25–27].
90 Among them, the hyper-core decomposition [26, 27] iden-
91 tifies a doubly nested hierarchy of mesoscopic subhyper-
92 graphs, the hyper-cores, composed of nodes progressively
93 more densely connected to each other through interac-
94 tions of increasing size. This technique provides a global
95 fingerprint of systems described using hypergraphs and
96 identifies structurally central mesostructures that play an
97 important role in higher-order dynamical processes [26].
98 This decomposition also comes with an associated cen-
99 trality measure for nodes, the hypercoreness, which is
100 based on the node structural position at the various in-
101 teraction orders [26].

102 The increasing attention to the development of frame-
103 works to handle time-varying and non-pairwise structures
104 speaks for the need of using both the temporal and the
105 higher-order nature of interactions to adequately describe
106 and model several complex systems and dynamical pro-
107 cesses. The integration of these two features has occurred
108 relatively recently within *temporal hypergraphs*, where hy-
109 peredges present specific activation times and duration,
110 describing evolving group interactions [15]. Some works
111 focused on defining procedures to construct temporal hy-
112 pergraphs from data [28, 29], others on the impact of
113 the hypergraph dynamics on dynamic processes [30, 31].
114 Only few attempts have been made to investigate the
115 temporal-topological properties of temporal hypergraphs
116 [29, 32–36], and a complete structural characterization is
117 still missing. Moreover, synthetic models of temporal hy-
118 pergraphs have been proposed to identify and replicate
119 the mechanisms that govern the evolution of empirical
120 systems [9, 35–38], but model-validation tools are still
121 scarce. Therefore, it becomes necessary to develop ded-
122 icated multi-scale characterization methods tailored for
123 temporal hypergraphs. These techniques are essential to
124 accurately describe empirical systems, construct and val-
125 idate synthetic models, and ultimately identify crucial
126 temporal structures for higher-order dynamic processes:
127 how does the higher-order structure evolve at different
128 scales over time? Are there persistent groups of nodes
129 exhibiting dense connections at different interaction or-
130 ders, or do these configurations change dynamically? Are
131 the most structurally central nodes always the same, or
132 do they undergo changes over time?

133 Here, we tackle such issues by proposing a multi-scale
134 method for the characterization of temporal hypergraphs
135 at different topological scales. By applying the hyper-
136 core decomposition to successive snapshots of a tempo-
137 ral hypergraph, and by following the evolution of the re-
138 sulting hierarchical structure, we are able to characterize
139 the structure and its evolution at different scales: macro-
140 scopically, following the evolution of the relative sizes of
141 the hyper-cores; mesoscopically, focusing on the dynam-
142 ics of specific hyper-cores; microscopically, following the

143 position of single nodes in the hyper-core structure over
144 time. Measuring the similarity between the hyper-core
145 structure at different times enables the quantification of
146 the structural stability of the system at different topo-
147 logical scales. We also define two time-aggregated hyper-
148 coreness centralities for nodes, based on the node instan-
149 taneous hypercoreness and its evolution, which together
150 provide an overall description of its structural behavior.
151 We apply the proposed approach to several data sets rep-
152 resenting systems of diverse nature. This enables us to
153 identify differences and similarities in their structure and
154 evolution, unveiling temporal patterns, and to establish
155 connections between structural properties and specific ac-
156 tivities within the systems. Finally, we illustrate how
157 the proposed method provides a model-validation tool for
158 synthetic models of temporal hypergraphs. To this aim,
159 we propose several models of activity-driven temporal hy-
160 pergraphs [9, 13, 39, 40] which progressively implement
161 mechanisms for the formation of group interactions of
162 increasingly complexity. We tune these models to mimic
163 the activity patterns of the interaction data sets and show
164 how, following the hyper-core decomposition over time,
165 we are able to distinguish between the hyper-core struc-
166 tures and dynamics generated by the models at different
167 topological scales, providing a quantitative comparison
168 between synthetic models and empirical hypergraphs.

169 The paper is organized in the following way: in Section
170 II A we describe the hyper-core decomposition and how
171 it provides a multi-scale method for the characterization
172 of temporal hypergraphs; in Section II B we define two
173 time-aggregated centrality measures for nodes; in Section
174 II C we present the empirical data sets considered, and in
175 Sections II D, II E we apply the proposed method to dif-
176 ferent data sets; in Section II F we show how our method
177 can be used as a model-validation tool, considering dif-
178 ferent hypergraph models; in Section III we summarize
179 the main results, discuss their implications and outline
180 some future perspectives. In order to avoid accumulating
181 too many technical details in the previous sections, we
182 leave the detailed presentation of several aspects of our
183 methodology to Section IV-Methods (on the hyper-core
184 decomposition in Section IV A, on the data preprocess-
185 ing in Section IV B, on reshuffling procedures in Section
186 IV C and on the temporal hypergraph models in Section
187 IV D).

188 II. RESULTS

189 A. Following the hyper-core decomposition of 190 temporal hypergraphs

191 Let us consider a time-varying hypergraph \mathcal{H} observed
192 over the time interval $(0, t_{max}]$. We consider a snapshot
193 representation of \mathcal{H} with temporal resolution τ [28], i.e.,
194 the interval $(0, t_{max}]$ is divided into $n = t_{max}/\tau$ time
195 windows of length τ : $\mathcal{H} = \{\mathcal{H}_t\}_{t=1}^n$, where in each time
196 window t the instantaneous hypergraph $\mathcal{H}_t = (\mathcal{V}_t, \mathcal{E}_t)$ is
197 an unweighted static hypergraph formed by the set \mathcal{V}_t
198 of nodes active at least once in $((t-1)\tau, t\tau]$ and by the
199 set \mathcal{E}_t of hyperedges active at least once in $((t-1)\tau, t\tau]$
200 (with $N_t = |\mathcal{V}_t|$ and $E_t = |\mathcal{E}_t|$). A hyperedge $e =$
201 $\{i_1, i_2, \dots, i_m\} \in \mathcal{E}_t$ represents a group interaction between

nodes $i_k \in \mathcal{V}_t \forall k = 1, \dots, m$: it consists in a set of m nodes, with $m \in [2, M_t]$, where $M_t = \max_{e \in \mathcal{E}_t} |e|$. We denote with $\Psi_t(m)$ the hyperedge size distribution in the time-window t [41].

We propose to characterize the structural evolution of the temporal hypergraph \mathcal{H} by applying the hyper-core decomposition procedure to each snapshot \mathcal{H}_t [26]. The hyper-core decomposition decomposes static hypergraphs into series of subhypergraphs of increasing connectivity, ensured by hyperedges of increasing sizes. Specifically, the (k, m) -hyper-core of the snapshot $\mathcal{H}_t = (\mathcal{V}_t, \mathcal{E}_t)$ is defined as the maximum subhypergraph that contains all the nodes $i \in \mathcal{V}_t$ involved in at least k distinct hyperedges of size at least m within the subhypergraph itself (see Methods and [26]).

The set of nodes belonging to the (k, m) -core but not to the $(k+1, m)$ -core forms the (k, m) -shell. Each node i in the temporal hypergraph can thus be assigned a time-varying m -shell index $C_m(i, t)$, which defines the maximum k such that i belongs to the (k, m) -hyper-core but not to the $(k+1, m)$ -hyper-core at time t . This leads to the definition of the hypercoreness $R(i, t)$ of node i in \mathcal{H}_t by [26]:

$$R(i, t) = \sum_{m=2}^{M_t} C_m(i, t) / k_{max}^m(t), \quad (1)$$

where $k_{max}^m(t)$ is the maximum connectivity at order m for the snapshot t , such that the $(k_{max}^m(t), m)$ -core is not empty, but the $(k_{max}^m(t) + 1, m)$ -core is empty. $R(i, t) \in [0, M_t - 1]$ summarizes the centrality properties of i with respect to the hyper-core decomposition at time t by taking into account its relative depth in the (k, m) -core structure at all interaction orders [26] [42].

By considering the hyper-core decomposition of the successive snapshots forming the temporal hypergraph, we can thus follow the temporal evolution of its higher-order hierarchical structure, and obtain a characterization of the higher-order dynamics at several scales, as we now discuss.

Macroscopic scale. The fraction of nodes within the (k, m) -hyper-cores, $n_{(k,m)}$, as a function of k and m constitutes the *filling profile* of the hyper-cores, and provides information on the distribution of nodes in the various cores and shells. Following its evolution across successive snapshots yields information on how the overall system's cohesiveness changes over time. The filling profile can indeed detect changes in the underlying higher-order hierarchical structure, since different distributions of nodes in the hyper-cores reflect different configurations of interactions in the nested hierarchy [26]: for instance, a smooth decay of $n_{(k,m)}$ with k and m suggests the presence of nodes progressively more densely connected with each other through interactions of larger sizes (homogeneously populated shells), while the alternation of plateaus and abrupt drops reveals the presence of a non-trivial structure, with nodes poorly or densely connected with each other, without intermediate behaviours (unevenly filled shells). Thus, the similarity between the hyper-cores filling profiles of two different snapshots, $n_{(k,m)}(t)$ and $n_{(k,m)}(t')$, provides a quantitative estimate of the stability of the macroscopic hyper-core structure over time. While several similarity measures can be defined between

the filling profiles of two hypergraphs, we consider here the root-mean-square deviation similarity, defined as follows for the filling profiles $a_{(k,m)}$ and $b_{(k,m)}$ of two static hypergraphs \mathcal{A} and \mathcal{B} with respective maximum connectivities $k_{max}^m(\mathcal{A})$ and $k_{max}^m(\mathcal{B}) \forall m$, and respective maximum hyperedge sizes $M_{\mathcal{A}}$ and $M_{\mathcal{B}}$:

$$\Sigma(\mathcal{A}, \mathcal{B}) = 1 - \sqrt{\frac{\sum_{k=1}^{\bar{K}} \sum_{m=2}^{\bar{M}} (a_{(k,m)} - b_{(k,m)})^2}{\bar{K}(\bar{M} - 1) - 1}}, \quad (2)$$

with $\bar{K} = \max_m \{\max\{k_{max}^m(\mathcal{A}), k_{max}^m(\mathcal{B})\}\}$ and $\bar{M} = \max\{M_{\mathcal{A}}, M_{\mathcal{B}}\}$ (in this way $\Sigma \in [0, 1]$) [43] [44]. The temporal similarity matrix $\Sigma(t, t') = \Sigma(\mathcal{H}_t, \mathcal{H}_{t'})$ provides then a way to explore the existence of various temporal patterns in the hyper-core decomposition of the system at different times, and to unveil the presence of stable periods, recurrences or sudden changes [7, 10, 45, 46] [47].

Mesoscopic scale. By following the hyper-core decomposition over time, it is moreover possible to study the temporal stability and changes occurring in subhypergraphs with specific structural roles. To this aim, we can consider a given set of shells or cores, and compare their sets of nodes A in two different snapshots t and t' through the Jaccard similarity $J(t, t') = |A_t \cap A_{t'}| / |A_t \cup A_{t'}|$. The matrix $J(t, t')$ quantifies the stability over time of the set of nodes forming the cores under scrutiny. In particular, we will here focus on the set of the most central hyper-cores of each snapshot, i.e. the (k_{max}^m, m) -hyper-cores $\forall m$. We can then determine whether these cores are stable, involving always the same nodes across snapshots, or whether their composition evolves, due to changes of connectivity of individual nodes: this can happen even when the macroscopic structure remains similar (as found in temporal networks where the most connected nodes can vary with time [48], or a core-periphery structure can be stable even when the composition of the core strongly fluctuates [10]).

Moreover, empirical data include sometimes meta-data (see Methods) describing properties or attributes of the nodes or hyperedges, and dividing them into classes based on their specific function or context. For instance, data describing social interactions can be enriched by information on the individuals involved (e.g., to which class they belong in a school environment, to which department or which role they have in a work environment). Such information makes it possible to study whether different groups or classes of nodes have different higher-order structural properties, and whether specific hyper-cores are preferentially composed by specific nodes or specific types of hyperedges. For instance, one can identify the most represented class in each hyper-core at each time, and follow over time which types of nodes or hyperedges are dominant in the most central hyper-cores.

Microscopic scale. At the node level, the hypercoreness $R(i, t)$ gives an instantaneous measure of the centrality of a node in each snapshot. It is thus possible, for each node of interest, to follow its trajectory in the hyper-core structure through the evolution of its hypercoreness. More precisely, in order to make the hypercoreness values comparable across different snapshots, we consider the temporal evolution of the relative position of each

node i in the hypercoreness ranking:

$$r(i, t) = \frac{R(i, t)}{\max_{j \in \mathcal{V}_t} \{R(j, t)\}}. \quad (3)$$

The evolution of $r(i, t)$ with t indeed reflects the movements that node i undergoes within the hierarchical structure, potentially navigating towards more central or more superficial cores.

The set of all $R(i, t)$ moreover provides an instantaneous node hierarchy within the time window t . Such a hierarchy might fluctuate from one snapshot to the next [48], and the Pearson correlation coefficient $\varrho(t, t') = \varrho(R(i, t), R(i, t'))$ of the nodes hypercoreness values between two time snapshots t and t' provides information on the stability of the node ranking over time, i.e., on how the nodes change their respective structural positions over time. Just as $\Sigma(t, t')$ for the global scale and $J(t, t')$ for intermediate scales, this measure can unveil correlation patterns at various time-scales: for example, a high and constant $\varrho(t, t')$ indicates that nodes tend to keep their relative structural positions over time, while constantly low values correspond to an unstable situation with nodes continuously changing place in the hierarchy.

Note that, as not all nodes are active in each snapshot, we can compute $\varrho(t, t')$ in two ways: (i) $\rho^*(t, t')$ takes into account only the nodes that are active in both t and t' , while (ii) $\rho(t, t')$ is computed considering all nodes active in at least one of them (setting the hypercoreness of inactive nodes to 0). The difference between $\rho(t, t+1)$ and $\rho^*(t, t+1)$ provides information on the structural properties of nodes just after entering the system or right before leaving it: $\rho \lesssim \rho^*$ indicates that nodes have mainly low hypercoreness when joining/leaving the system, while $\rho \ll \rho^*$ indicates that nodes joining/leaving the system tend to be central.

B. Time-aggregated hypercoreness centralities

The hypercoreness centrality of nodes in static hypergraphs has been shown to provide information on their importance for dynamic processes involving higher-order interactions unfolding on such hypergraphs [26]. Many processes however unfold on time-varying hypergraphs [30, 31], hence a time-aggregated ranking of nodes summarizing the evolution of their instantaneous coreness could prove useful.

We first define **the snapshot activity** $a_w(i) \in [0, n]$, given by the number of time windows in which node i is active, and **the average number of interactions when active** $\bar{h}(i) = D(i)/a_w(i)$, where $D(i)$ is the total number of hyperedges in which i is involved in the temporal hypergraph. We then introduce two time-aggregated centrality measures that summarize the positions of the nodes in the hyper-core structure over time:

- **the aggregated hypercoreness** W :

$$W(i) = \sum_{t=1}^n \frac{R(i, t)}{\max_{j \in \mathcal{V}_t} \{R(j, t)\}} = \sum_{t=1}^n r(i, t), \quad (4)$$

takes into account how deep i is in the hyper-core structure at the various interaction orders in each

time window, and simply aggregates this information over time.

- **the activity-averaged hypercoreness** \bar{W} :

$$\bar{W}(i) = \sum_{t=1}^n \frac{r(i, t)}{a_w(i)} = \frac{W(i)}{a_w(i)}, \quad (5)$$

averages W over the activity of the nodes.

W and \bar{W} provide complementary information. Indeed, a high W can be obtained either for a node i that is very active (high $a_w(i)$) but not very central (small $r(i, t)$) or for a node j that is not very active (low $a_w(j)$) but central when active (high $r(j, t)$). These two situations are distinguished when taking into account also \bar{W} , as $\bar{W}(i)$ will then be small while $\bar{W}(j)$ will be large. Together, the time-aggregated hypercoreness measures $W(i)$ and $\bar{W}(i)$ thus provide a two-dimensional picture taking into account both the activity of nodes and the evolution of their relative centralities over time.

C. Empirical temporal hypergraphs

The approach outlined is general and can be applied to empirical data of higher-order interactions evolving over time describing a variety of systems. In the following, we showcase its interest using: a data set of scientific collaborations [49, 50], several data sets of physical proximity interactions between individuals in various environments [51–59] (a hospital [55], a conference [53], three schools [56–58], a university [59] and a workplace [52, 53]), and a data set of email communications [60–62]. These data sets present different statistical, topological and temporal properties (e.g., interaction size distribution, temporal patterns due to system-specific activities). Full details on all the data sets and on the preprocessing procedures are available in the Methods Section (Section IV) and in the Supplementary Material (SM). In the main text we specifically analyse data describing three different systems, while results for the other data sets are reported in the SM. In particular, here we consider:

- the scientific collaborations data set of the American Physical Society (APS), which provides the list of papers published in APS journals from 1893 to 2021 [49, 50]. We build a temporal hypergraph (see Methods) in which each node corresponds to an author, each hyperedge represents a paper connecting its co-authors and is endowed with a label indicating the journal in which the paper was published.
- a data set of face-to-face human interactions in a hospital (LH10), collected within the SocioPatterns collaboration [51, 55]. The data set has a temporal resolution of 20 seconds and covers a period of 96 hours. We build a temporal hypergraph in which each node corresponds to an individual and each hyperedge represents a group interaction, defined with a temporal resolution of 5 minutes (see Methods) [20]. Each node is assigned with a label indicating its social role: **Med** for doctors, **Param** for nurses, **Admin** for administrative staff, and **Patient** for patients.

- a data set of proximity human interactions in a university, collected within the Copenhagen Network Study (CopNS) [59]. The data set has a temporal resolution of 5 minutes and covers a period of 4 weeks. We build a temporal hypergraph from the data by considering each individual as a node, and each hyperedge as a group interaction with a temporal resolution of 5 minutes (see Methods) [36].

For the university data set, we also show how the analysis of the hyper-core structure over time can contribute to the validation of models of time-varying hypergraphs.

D. Dynamics of the higher-order structure of scientific collaborations

We represent the APS scientific collaborations data set through a time-varying hypergraph in which each node corresponds to an author and each hyperedge represents a paper connecting its co-authors (see Methods). We consider a 5-years temporal resolution, i.e., each temporal snapshot is formed by all papers published in a 5-years time window (see SM for a different temporal resolution), and we consider the period 1962-2021 (earlier years having only much smaller numbers of nodes and hyperedges).

Figure 1a shows the evolution of the global hyper-cores structure as given by the filling profiles, which do not simply expand in a monotonous fashion as the numbers of nodes and hyperedges increase over the years. Initially the system presents only (k, m) -hyper-cores with low connectivity k , especially for large hyperedge sizes m ; then, the filling profile undergoes an expansion towards higher k and higher m values. At first, k_{max}^m increases for high interaction orders m and only later at low orders. Furthermore, the increase in k_{max}^m is non-monotonic with respect to time, especially for low m : k_{max}^m for $m \gtrsim 2$ grows up to a maximum in the 1997-2001 snapshot, and then decreases and stabilizes in the following years (as we will discuss below, this behavior can be traced back to a specific scientific community and its collaboration dynamics). Thus, the cohesiveness of the scientific community first increased through connected large size collaborations, then an increase in cohesiveness occurred at all orders until 1997-2001. The cohesiveness of the community then relaxed to a lower but stationary level in the last 20 years.

Although the size of the interactions and the density of collaborations change over time, the overall structure of the filling profiles remains similar instead (Fig. 1a). In fact, the hyper-cores always present a rapid and progressive emptying of the cores as k and m increase: superficial shells (low k) are densely populated, and shells become gradually less populated with increasing k and m . The root-mean-square deviation similarity $\Sigma(t, t')$ between the hyper-cores filling profiles at time t and t' presents very high values for all pairs (t, t') (Fig. 1b), indicating a stable structure: the similarity is particularly high between consecutive snapshots (Fig. 1e), and decreases monotonically when $|t' - t|$ increases.

We investigate the mesostructural level through the similarity $J^*(t, t')$ between the sets of nodes belonging to the most central cores, i.e. to the (k_{max}^m, m) -hyper-cores $\forall m$ at different times. Figure 1c,f shows that the

stability of the central cores is low, even between adjacent time windows. This is not only due to the fact that the set of authors change over time, as J^* is much lower than the Jaccard coefficient J_N between the sets of authors in different time windows. $J^*(t, t')$ moreover decreases to 0 as soon as the time difference $|t' - t|$ exceeds 2-4 time windows, indicating a completely different composition of the central hyper-cores. Note that a tendency to increase the stability of the central cores can be seen until ≈ 2010 (Fig. 1c,f), although it decreases again afterwards. Overall the J^* values remain low, indicating that the nodes sitting in the most central hyper-cores change over time.

We further explore this instability using the correlation $\rho(t, t')$ of nodes hypercoreness across different time windows, as shown in Fig. 1d,g. A positive correlation is observed between the hypercoreness values of nodes in successive snapshots, but the correlation $\rho(t, t+1)$ computed using all nodes active at least once in $(t, t+1)$ is lower than $\rho^*(t, t+1)$, which takes into account only nodes active in both snapshots (Fig. 1g). As discussed above, this indicates that some nodes with high centrality leave the system, and/or nodes enter the system and gain immediately a central position. As the temporal distance $|t' - t|$ increases, the correlation $\rho(t, t')$ progressively decreases. Moreover, the correlations tend to increase with t : $\rho(t, t+1)$ increases with t and the decrease of $\rho(t, t')$ with $t - t'$ becomes slower (Fig. 1d,g), indicating an increased stability in centrality rankings as time evolves.

The correlation between hypercoreness values decays to zero in approximately 3-5 time windows and then reaches negative values: this suggests a progressive inversion of the rankings over time, with nodes successively increasing and decreasing their hypercoreness and rankings, as driven by the unfolding of their academic careers. Figure 2 indeed gives some examples of the evolution of individual nodes' relative hypercoreness $r(i, t)$, which are a reflection of the academic trajectories of the corresponding scientists. Some nodes have a bell-shaped hypercoreness profile, entering the system with a low centrality, progressively moving towards the more central cores and then back to lower ranks. This can describe the academic trajectory of a young researcher, who enters into the scientific community, becomes central and then progressively leaves the community due to retirement or a change in the topic/journals reference of their research. Other nodes present instead a rather stable ranking, and, for individuals having entered the system more recently, only the upward trend of increasing centrality is observed.

To characterize the nodes' overall behaviours, we moreover compute their time-aggregated centrality measures, and show the results in Fig. 3. On average, the aggregated hypercoreness $\langle W \rangle$ increases with the activity snapshot a_w (Fig. 3a), but a large variability in the values of W is observed at given a_w . Some nodes can be very active but display a low centrality, while nodes with moderate activity can reach large values of W . The average number of interactions per active window \bar{h} is also only weakly correlated with W , and the nodes with highest W do not coincide with those with largest \bar{h} (see Fig. 3b). Finally, the aggregated and activity-averaged hypercoreness, W and \bar{W} , also do not produce the same ranking (see Fig. 3c). Some nodes are not often active (low a_w) with medium-low W but high \bar{W} : these au-

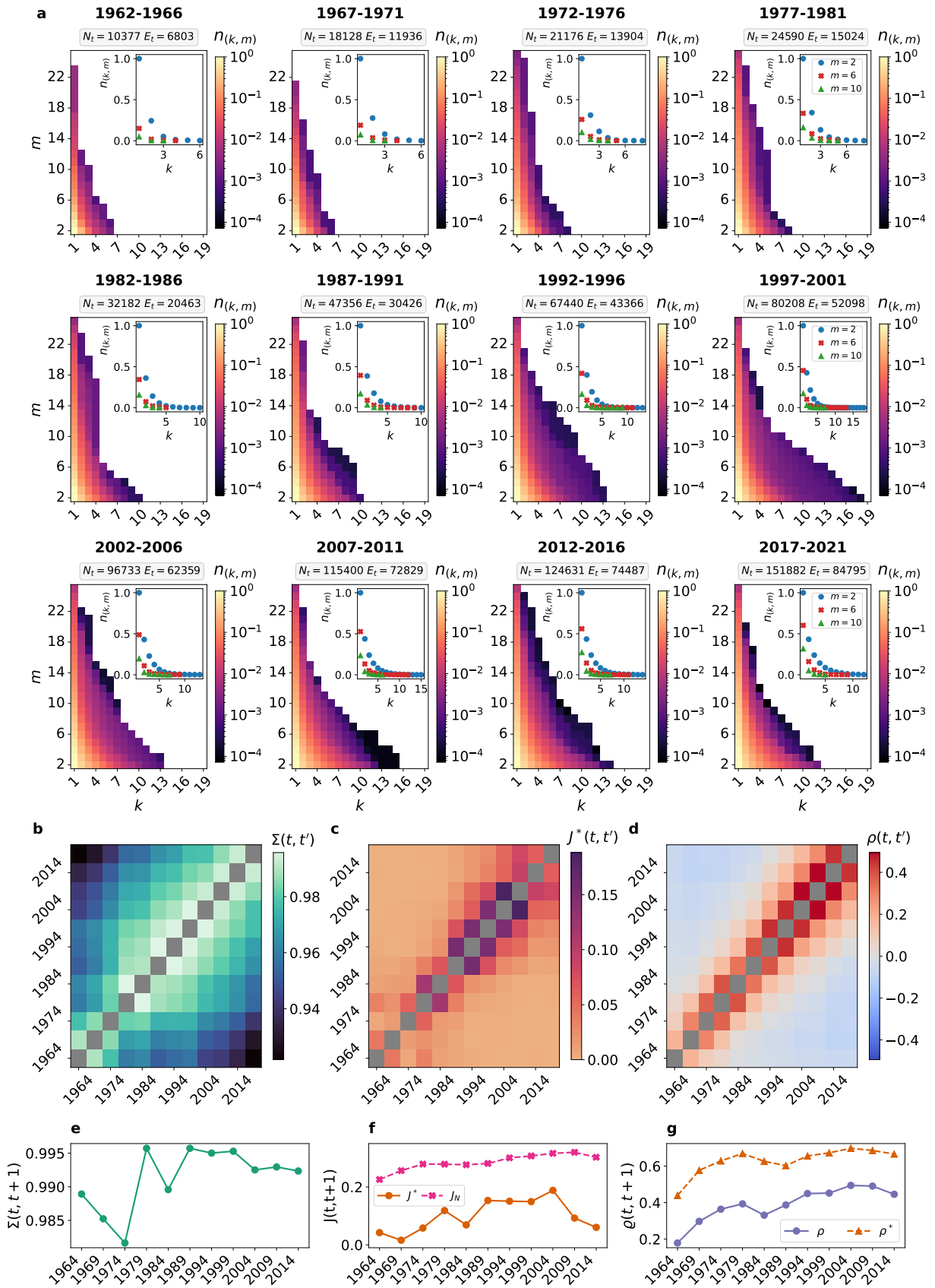


FIG. 1.

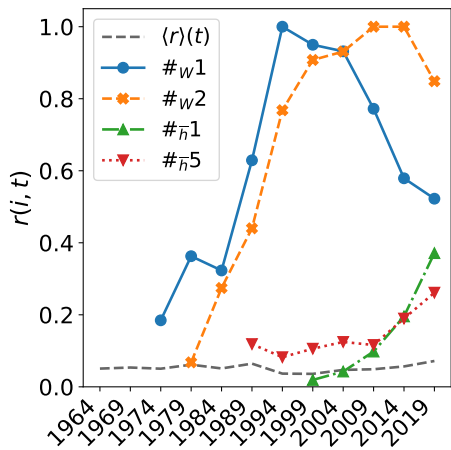


FIG. 2.

547 thors appear in few windows but within very connected
 548 communities, therefore are very central on average when
 549 active but their low a_w make them less relevant in ag-
 550 gregated terms. Other nodes are very active (high a_w)
 551 with medium-high W but relatively low \bar{W} : such authors
 552 are often active either with a low centrality or with non-
 553 monotonous hypercoreness profile (see Fig. 2). Overall,
 554 the combined information of W and \bar{W} provide a more
 555 complete description of nodes structural behavior on the
 556 whole time span than when considering only one of these
 557 centralities.

558 We finally leverage the fact that each hyperedge repre-
 559 senting a scientific article is labelled by the journal it was
 560 published in to examine the importance of the various
 561 APS journals in the hyper-core structure. The APS jour-
 562 nals can be interdisciplinary (e.g. PRL) or specialized in
 563 a specific research field (e.g. PRC for nuclear physics,
 564 PRD for high-energy physics, PRB for condensed matter
 565 physics), thus representing a specific research area [50]
 566 (see SM).

567 For each (k, m) -core we consider all the hyperedges it
 568 contains and their labels, and we identify the dominant
 569 journal (namely, whose frequency exceeds 0.5; if no jour-
 570 nal is represented by more than half of the hyperedges,
 571 we consider that no journal dominates) [63]. Figure 4a
 572 shows the resulting evolution of the hyper-cores domi-
 573 nant journal. Initially, PR and PRL dominate within all
 574 the hypercores, since they were the only available jour-
 575 nals together with RMP (not shown in the figure, see
 576 SM). Then, the more superficial cores present a mixed
 577 composition, while the most central ones are first domi-
 578 nated by PRL in the period 1962-1981; subsequently in
 579 1982-1986, central cores are mostly formed by the high-
 580 energy physics community (PRD) for large collaboration
 581 sizes, while at low order the nuclear physics area domi-
 582 nates (PRC). Starting from 1992, PRC dominates the
 583 most central hyper-cores at all orders: the non-monotonic
 584 behavior observed in the core structure, with the maxi-
 585 mum connectivity in 1997-2001, is predominantly due to
 586 interactions within the nuclear physics area. This could
 587 be due to several discoveries in the field occurring in the
 588 preceding years (e.g. the discovery of the W and Z bosons
 589 [64] or the discovery of top quarks [65, 66]), which boosted
 590 collaborations in the community, favouring and increas-

591 ing cohesion. After this phase the nuclear physics area
 592 remains overall dominant. Moreover, this non-monotonic
 593 behavior can also be identified in the hyper-core decom-
 594 position of the hypergraphs obtained by considering only
 595 the papers published in PRC (see SM). Recently, the con-
 596 densed matter physics community (PRB) is also expand-
 597 ing its contribution to the central cores at low interaction
 598 orders. The relative contribution of the scientific commu-
 599 nities to the set of the most central cores is summarized
 600 in Fig. 4b: PRL is the dominant journal in the first
 601 time windows, while the share of PRC increases rapidly
 602 starting in the 80s; the share of PRB becomes also im-
 603 portant from 2012-2016 and in 2017-2021 new journals
 604 start gaining relevance (e.g. PRX).

605 As the number of scientists and articles in various fields
 606 are neither homogeneous nor constant, we check whether
 607 such patterns are simply due to the relative abundance
 608 of authors and articles in the different journals. To this
 609 aim, we build a randomized version of the temporal hy-
 610 pergraph, which preserves in each time window the hy-
 611 pergraph structure and the total number of interactions
 612 of each order for each label, but destroys any correlation
 613 between the nodes and the label of the hyperedges in
 614 which they participate (see the reshuffling procedure in
 615 Methods). We consider 50 randomized realizations and
 616 for each hyper-core we estimate the average frequency
 617 of each label. The patterns of topic dominance in the
 618 most central cores is significantly different in the reshuf-
 619 fled version compared to the empirical case (see Fig. 4b,c
 620 and SM). For example, in the reshuffled case PRA, PRB
 621 and PRE are significantly more represented in the central
 622 cores, while PRC is instead less represented than in the
 623 original data.

624 It is also possible to consider a different time resolution
 625 for building the temporal hypergraph, to investigate e.g.
 626 the dynamics at shorter time-scales, or to focus on one
 627 specific scientific community by considering the hyper-
 628 graph formed by articles published in one specific journal.
 629 We refer to the SM for some results in such directions.

630 E. Higher-order structure dynamics of interactions 631 in a hospital

632 We now consider the data set of face-to-face interac-
 633 tions in a hospital (LH10), represented through a time-
 634 varying hypergraph where nodes correspond to individu-
 635 als and hyperedges to group interactions (see Methods).
 636 We first study differences in the daily aggregated hyper-
 637 graph structures, i.e., we aggregate the temporal hyper-
 638 graph over 24-hours time windows (thus obtaining $n = 4$
 639 time windows).

640 The maximum size of interactions M_t and the maxi-
 641 mum connectivity values $k_{max}^m(t) \forall m$, i.e. the cohesive-
 642 ness of the system, are rather stable over different days
 643 (Fig. 5a,b). However, nodes are differently distributed
 644 within the cores. On the first day, the population of the
 645 (k, m) -cores features sharp drops when k increases, fol-
 646 lowed by plateaus: these correspond to densely popu-
 647 lated shells at small k followed by almost empty shells.
 648 In other days, the structure instead presents a more
 649 progressive emptying of the cores as k increases, hence
 650 shells are populated more homogeneously (even if some

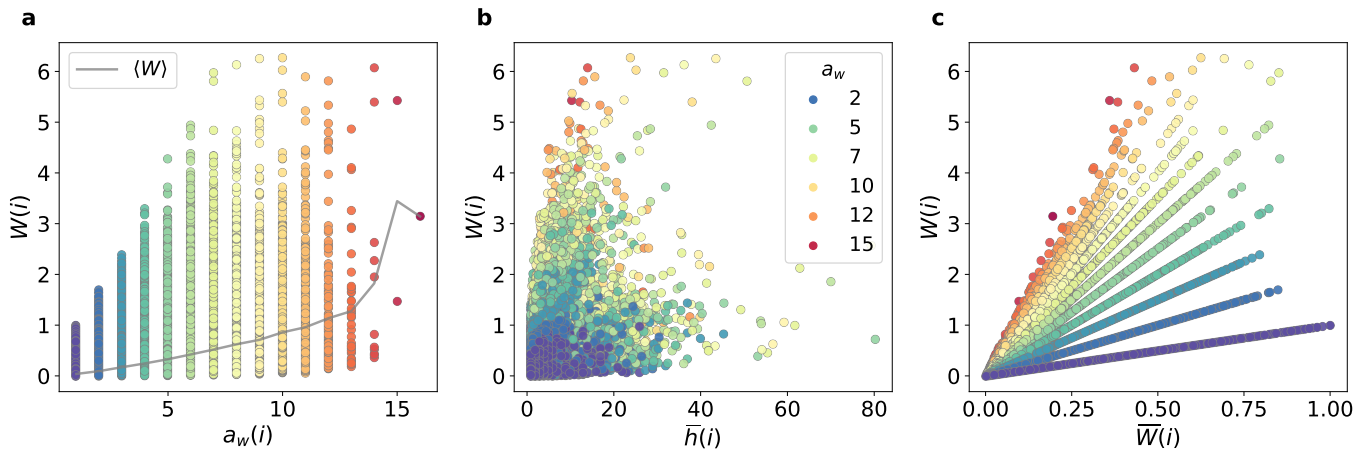


FIG. 3.

651 jumps and plateaus of reduced sizes are still present).
 652 The root-mean-square deviation similarity $\Sigma(t, t')$ be-
 653 tween the hyper-cores filling profiles at time t and t' still
 654 presents high values for all pairs (t, t') (see Fig. 5c), how-
 655 ever the similarity is lower than the one observed for the
 656 APS data set. Moreover, the similarity Σ between con-
 657 secutive snapshots increases over time (Fig. 5f).

658 Mesoscopically the system is quite stable (see Fig.
 659 5d,g): the similarity $J^*(t, t')$ between the nodes in the
 660 most central cores at time t and t' presents medium-high
 661 values, and $J^*(t, t')$ slightly decreases when increasing
 662 $|t' - t|$ and in consecutive time windows it still assumes
 663 values close to the similarity of the entire population J_N ,
 664 even if decreasing over time. The composition of the most
 665 central cores is thus quite stable, therefore in general the
 666 nodes maintain the same position in the core structure.
 667 This is confirmed by the correlation $\rho(t, t')$ in the nodes
 668 hypercoreness between two snapshots (see Fig. 5e,h).
 669 The correlation $\rho(t, t')$ presents high values. As we will
 670 explore further below, this stability in the composition
 671 of central cores and in the behavior of the nodes is due
 672 to the difference in the roles played by the different indi-
 673 viduals in the hospital, which limits the mobility of the
 674 nodes in the hyper-core structure.

675 Note that, even if the position of the nodes in the
 676 hyper-core structure is fairly stable over time, the evolu-
 677 tion of the hypercoreness $r(i, t)$ for single nodes can
 678 show different trajectories. This is evident when disag-
 679 gregating by social role, as for the examples in Fig. 6:
 680 the nodes can present a stable dynamic with a constant
 681 position in the core structure, as shown by the patient
 682 and the paramedic cases, or a non-monotonic dynamic,
 683 with movements from more central cores towards more
 684 superficial ones and vice-versa, as for the doctor and the
 685 administrative staff member.

686 These different behaviours are summarized by the
 687 time-aggregated centrality measures. In general the ag-
 688 gregated hypercoreness W increases with the snapshot
 689 activity a_w (see Fig. 7a), however nodes with the same a_w
 690 can have very different W . Analogously, W and the av-
 691 erage number of interactions when active \bar{h} are positively
 692 correlated, but there are outliers, which produce differ-
 693 ent top positions in the corresponding rankings (see Fig.
 694 7b). By taking the structure into account, the aggregated

695 hypercoreness can thus provide a different and more de-
 696 tailed information than the activity or the average num-
 697 ber of interactions. The aggregated and activity-averaged
 698 hypercoreness show that the nodes that are globally rel-
 699 evant are also relevant, on average, when active (see Fig.
 700 7c). Nevertheless, the produced rankings are still dif-
 701 ferent since some nodes are relevant when active (high
 702 \bar{W}), but not globally (low W). By combining the two
 703 time-aggregated hypercoreness measures we obtain infor-
 704 mation on the different overall behaviors of the nodes (see
 705 Fig. 6).

706 We finally expose strong differences in the temporal
 707 and structural properties of specific roles in the hospital.
 708 Figure 7 shows that the activity a_w is quite independent
 709 of the social role; however, the patients have a homoge-
 710 neous behavior occupying always the lower positions in
 711 all the rankings produced by the other time-aggregated
 712 centrality measures; on the contrary the nurses, doctors
 713 and administrative staff present a more heterogeneous
 714 behaviour, presenting a wide range of centrality values.
 715 Nurses constitute the most structurally and temporally
 716 relevant group according to all the time-aggregated cen-
 717 trality measures, always occupying the top positions of
 718 the rankings (see Fig. 7).

719 The nurses have a key role also mesoscopically: in each
 720 (k, m) -hyper-core indeed, we identify the dominant social
 721 role when possible by checking whether more than half
 722 of the nodes of a core belong to one category. In the
 723 superficial cores it is not possible to identify a dominant
 724 role, however in the most central cores the nurses dom-
 725 inate in all time windows and at all interaction orders
 726 (see Fig. 8a). Nurses thus constitute the most densely
 727 connected social group at all the orders of interaction,
 728 thus the interactions structure in the most central cores
 729 is attributable to their activities.

730 The dominant role of nurses is further highlighted
 731 microscopically by considering the evolution of the
 732 average hypercoreness $r(i, t)$ within each specific class
 733 (see Fig. 8b). All roles present a quite stable average hy-
 734 percoreness: patients and nurses present a hypercoreness
 735 notably lower and higher than the average, respectively,
 736 while doctors and administrative staff are close to the
 737 average behavior. Moreover, if we consider the instan-
 738 taneous ranking produced by the hypercoreness and

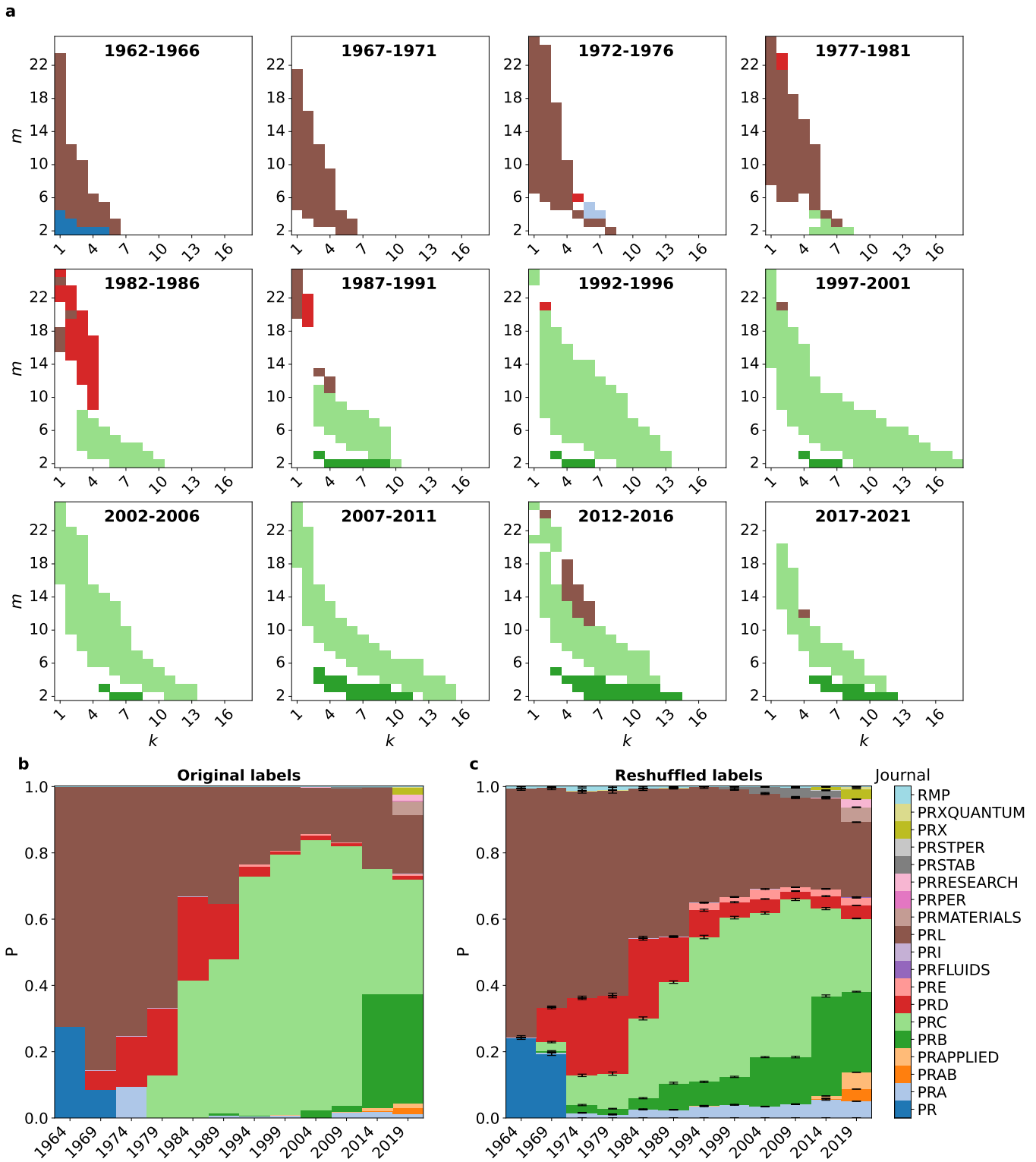


FIG. 4.

739 estimate the frequency of each role, we find that nurses
 740 always dominate the top positions (see Fig. 8c). This
 741 pattern is not due to a difference in numbers of nodes or
 742 hyperedges, as we check by comparing the results with a
 743 reshuffled data set in Fig. 8d: we generate 50 random
 744 realizations of the hypergraph, which completely preserve
 745 in each time window the structure of the hypergraph and
 746 the total number of nodes with each label, but destroys
 747 correlations between the labels of interacting nodes (see

748 the reshuffling procedure in Methods). The frequencies
 749 of the different social roles in the top positions of the
 750 hypercoreness ranking, averaged over all the realizations,
 751 shows strong differences compared to the original case.
 752

753 While we have here focused on the changes occurring
 754 between different days, it is possible to consider a differ-
 755 ent temporal resolution to focus e.g. on specific activities
 756 in the system occurring at a different time scales: in the

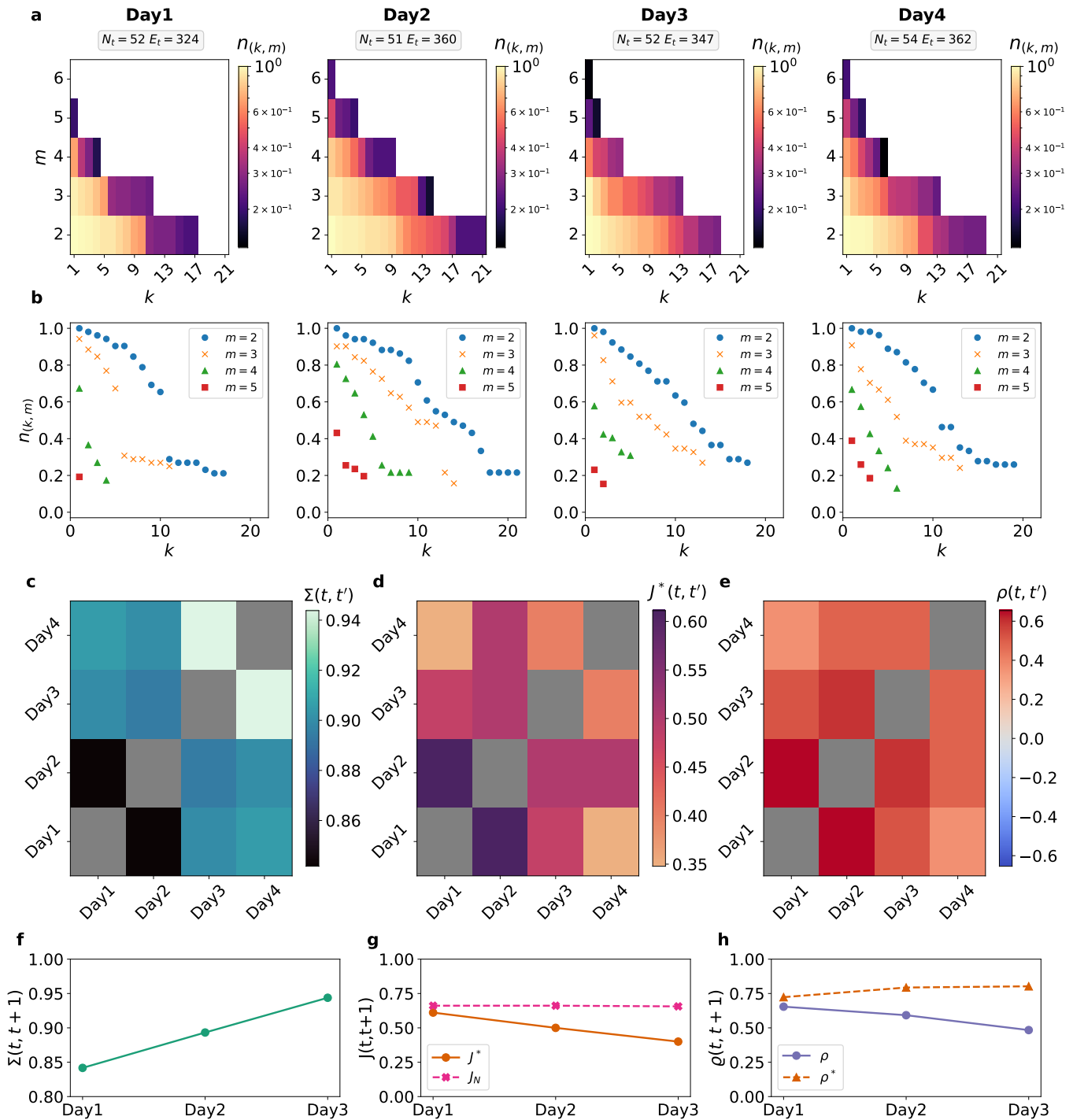


FIG. 5.

757 SM we consider as an example the evolution occurring
 758 within a single day with 2-hours time windows.

759 In the SM we also apply the proposed analysis to data
 760 sets describing interactions between individuals in differ-
 761 ent contexts (see Methods). In some contexts, the com-
 762 position of the hyper-cores present a strong structural
 763 variability and instability: this corresponds e.g. to con-
 764 ferences or workplaces where different days can bring very
 765 different patterns of connections. A more stable structure
 766 is obtained in others, with high stability of the cores com-
 767 position, e.g. systems in which patterns of interactions
 768 are repeated over time due to role and activities con-
 769 straints, such as in schools and hospitals (see SM). Such

770 differences in the results highlight and confirm the inter-
 771 est of following the hyper-core decomposition over time
 772 as a characterization tool for temporal hypergraphs.

773 F. A validation tool for time-varying hypergraph 774 models

775 We now illustrate how the hyper-core decomposition
 776 can also help with the validation of synthetic models of
 777 temporal hypergraphs. More precisely, it can serve as
 778 a tool to quantitatively validate whether a model repro-
 779 duces given hierarchical structures and structural dynam-

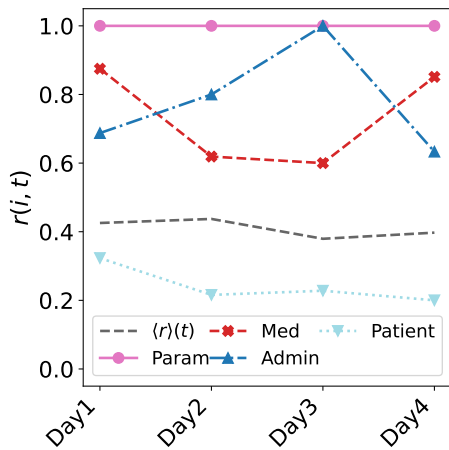


FIG. 6.

ics of interest, such as those of an empirical temporal hypergraph, at several topological and temporal scales. To showcase the potential of this as a tool, we consider several models of temporal hypergraphs of increasing complexity, and tune them to reproduce the activity patterns of a data set. We then apply the previously described approach to each model and to the original data set, identifying differences among the models, and ultimately investigating which model ingredients make it possible to generate a non-trivial hierarchical structure that resembles the one found in the data.

For simplicity, we consider models within the class of activity-driven (AD) networks: these models are based on simple mechanisms for the formation of interactions [13], and can be refined to include increasing complex realistic features and tuned to reproduce many properties of empirical data sets [40, 67–70]. We consider here several generalizations taking into account higher-order interactions, in a similar spirit as [9, 37]. In each model, we consider a population of N nodes: each node is assigned at each time t an activity parameter $a_t(i)$, which represents the node propensity to generate interactions and sets its activation rate (Poissonian activation dynamics). When a node is active, it generates a hyperedge of size m , drawn from a distribution $\Psi_t(m)$ (which potentially depends on the time step t). The remaining $(m-1)$ nodes are selected in the population with mechanisms depending on the specific AD model. We consider the following models:

- **Higher-order activity-driven model (HAD).**

This model is the hypergraph generalization of the standard AD network [13] and of the simplicial activity-driven model (SAD) [9]. Each active node creating an hyperedge of size m chooses the $m-1$ nodes to interact with uniformly at random from the whole population. This model takes into account only the heterogeneity of the agents behaviour, through their activities, and the one of the size of the groups. Interactions are instantaneous and there is no memory between successive time steps.

- **HAD model with attractiveness (HADA).**

This model corresponds to the hypergraph generalization of the AD network with attractiveness

[39, 40, 69, 70]. Each node is also assigned with an attractiveness parameter $b_t(i)$, which defines the intensity with which the node attracts active interactions. Each active node, to create an interaction of size m , selects the $m-1$ other nodes in the population randomly with probability proportional to their attractiveness b . The interactions are instantaneous and there is no memory. We consider $b_t(i) = a_t(i) \forall i$ at each time, i.e. the most (less) active nodes are also the most (less) attractive ones, as observed in empirical systems [69, 70].

- **HAD model with memory (HADAM).**

This model is the HADA with the introduction of an additional memory mechanism, similar to that proposed in the AD networks with memory [67, 68]. For each active node i , we denote by $l_t(i)$ the number of other nodes with which it has already interacted in previous time steps. The active node i , to create an interaction of size m , selects the $m-1$ other nodes (i) with probability $p_t(i) = 1/(1+l_t(i))$, among those not yet encountered, (ii) with probability $(1-p_t(i))$ among those already met. These nodes are selected: in the former case, with probability proportional to their attractiveness $b(j)$; in the latter case, with probability proportional to their attractiveness $b(j)$ and to the number of times they have already met with the active node w_{ij} .

Each model can be fed by empirical data in the following manner. Given an empirical temporal hypergraph \mathcal{H} and its snapshot representation $\{\mathcal{H}_t\}_{t=1}^n$, for each model we consider the same population size as the empirical hypergraph; moreover, we use the empirically observed hyperedges size distribution $\Psi_t(m)$ at each time step, and we tune the activities $a_t(i)$ so that the total number of interactions at each time, n_t^{tot} , and the total number of interactions in which each node is involved, $n_t(i)$, replicate the empirical ones (see Methods for more details on the hypergraphs generation).

Here specifically, we consider the data set of human interactions in a university (CopNS), represented through a temporal hypergraph where nodes correspond to individuals and hyperedges to group interactions (in the SM we also apply the same analysis to the hospital data set). Once we have generated the three synthetic temporal hypergraphs, we aggregate both data and models on 1-day time windows (see Methods). We then apply the hypercore decomposition to each time window and compare the resulting structures and their temporal evolution at this time scale. We mainly focus here on the first working days of the first week of the data, and we show in the SM that similar temporal and structural patterns are obtained also for other days and weeks.

The original data set presents a non-trivial filling of the cores, with significant differences over time (see Fig. 9a): on Monday the (k, m) -cores present a rapid emptying for all orders when k increases, with a rapid drop in the population (densely populated shells), followed by an extended plateau (empty shells); a similar structure is obtained on Wednesday and Thursday, but with some differences in the drops widths, in the plateaus extensions and in the maximum connectivity values; on Tuesday instead, the structure is very different, the maximum

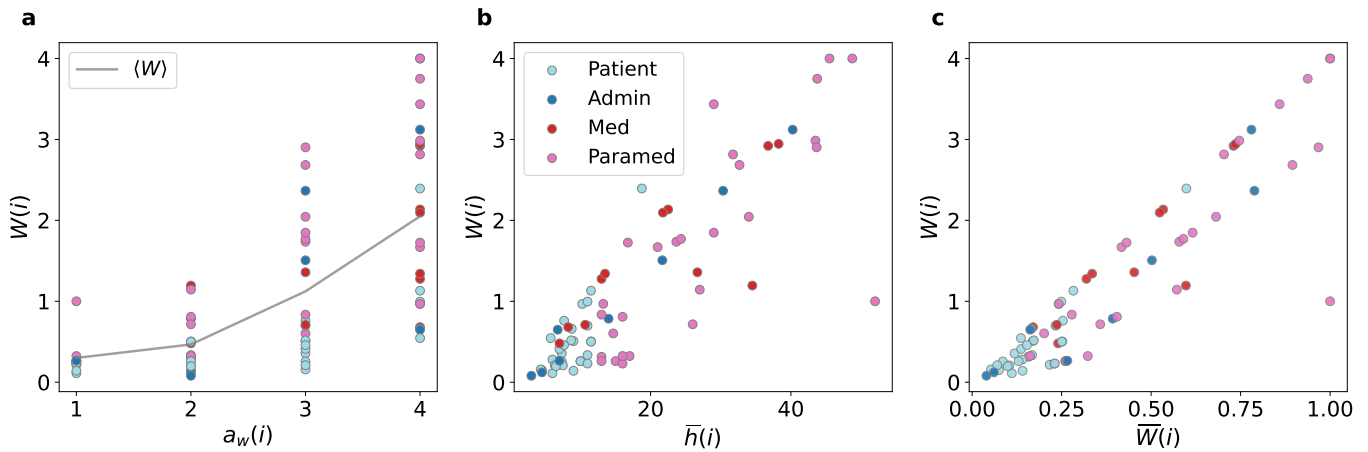


FIG. 7.

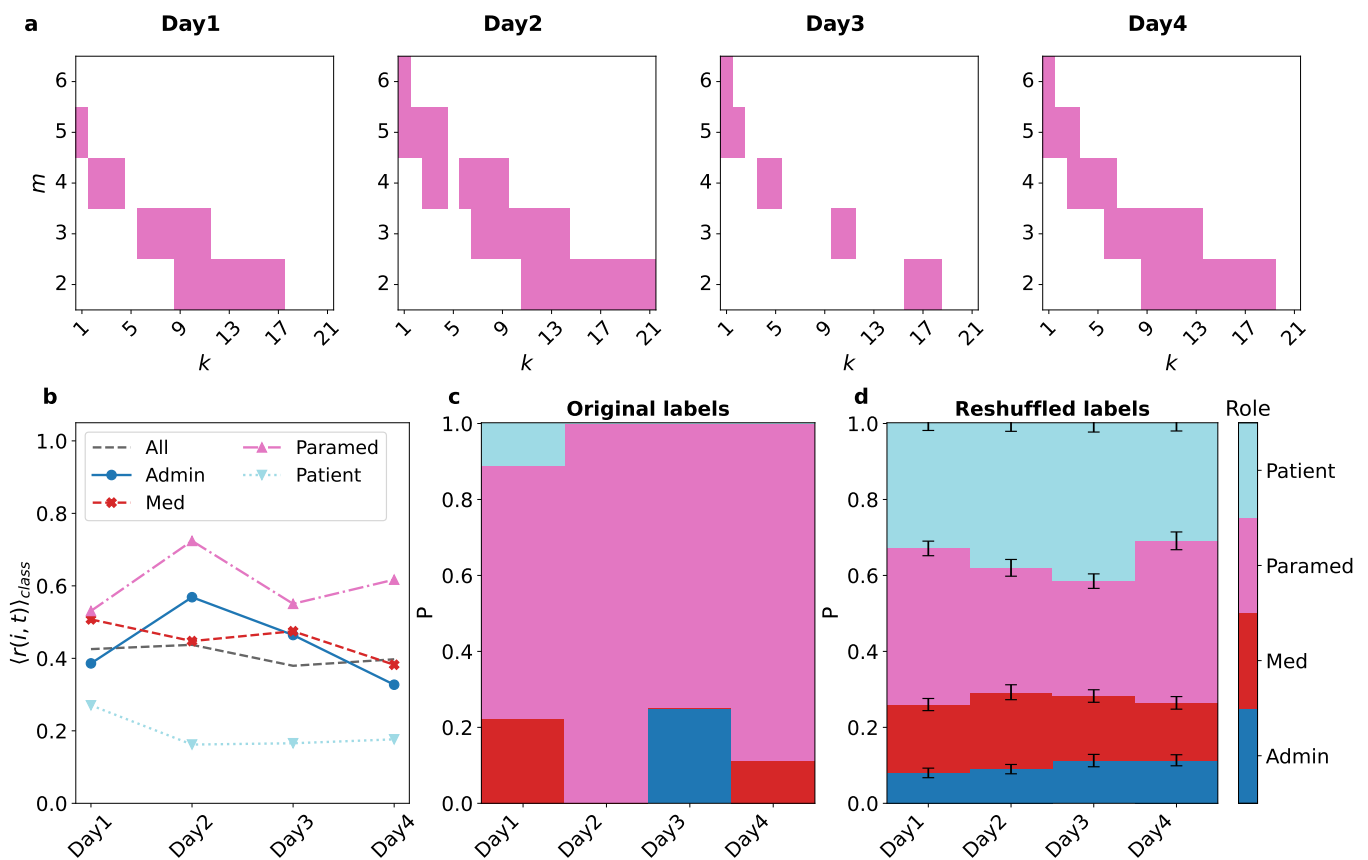


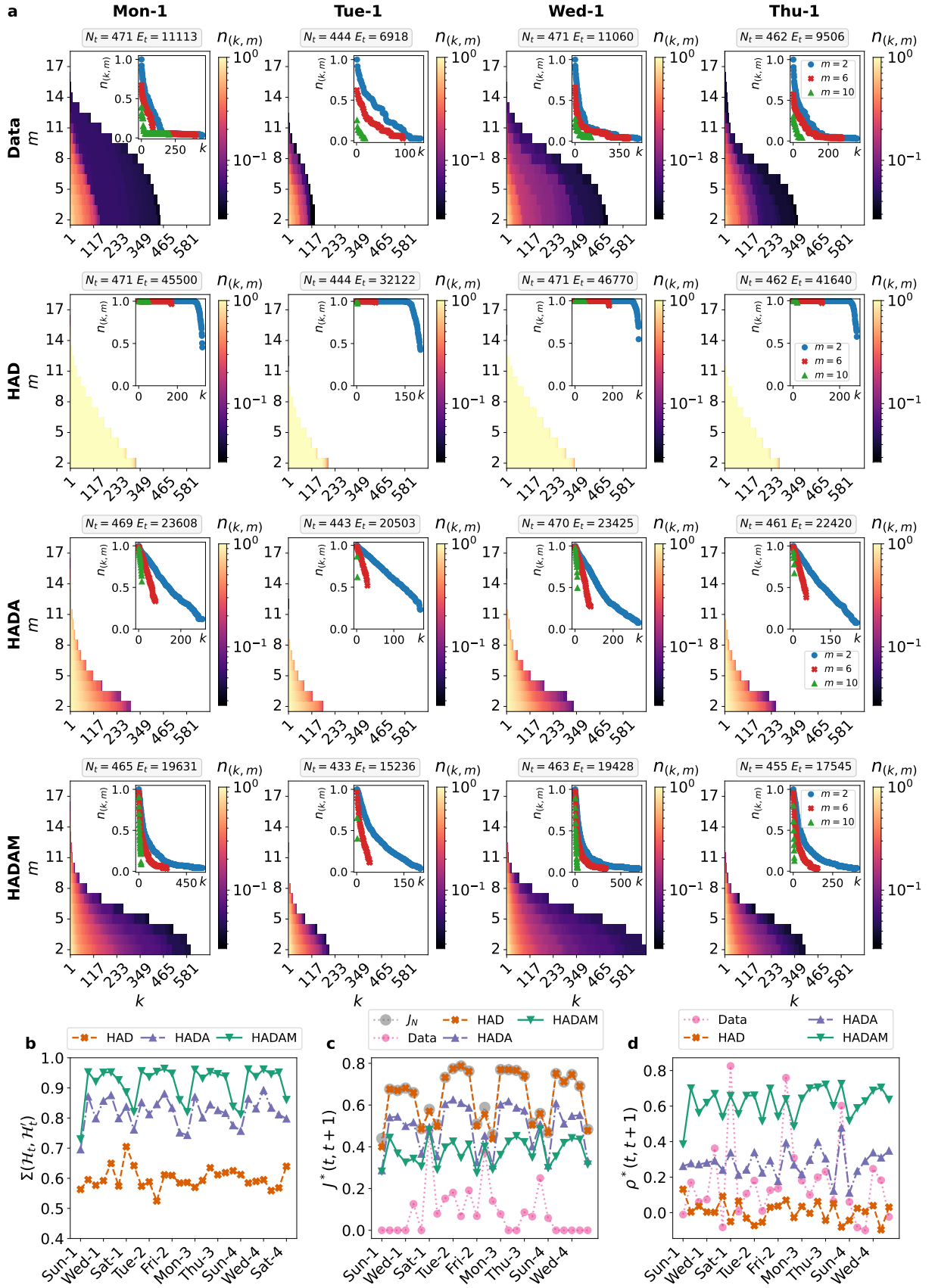
FIG. 8.

886 connectivity values are much lower and the plateau observed in the other time windows is almost absent. These
 887 filling profiles suggest the presence of a rich hierarchical structure in the hypergraph that changes over time.
 888
 889

890 The HAD model, despite replicating the activities and
 891 hyperedge distribution sizes of the data, has a very different hyper-core decomposition, which does not display
 892 any hierarchical structure (Fig. 9a): all (k, m) -cores are equally populated by the whole population until
 893 $k \sim k_{max}^m$, then $n_{(k,m)}$ quickly collapses to zero; all the shells are empty apart for those with $k \sim k_{max}^m$ which
 894 contain the entire population. The model thus does not replicate the empirical hierarchical structure nor its evolution,
 895
 896
 897
 898

899 neither mesoscopically, since all cores coincide with the entire population, nor microscopically, since all the nodes
 900 have the same position in the core structure. This is expected due to the interaction mechanism of the model
 901 —which generates a completely mean-field structure.
 902
 903

904 By contrast, the temporal hypergraph obtained from the HADA model does present a hierarchical structure:
 905 the population of the (k, m) -cores decreases progressively and smoothly with k at all orders m , indicating the presence
 906 of uniformly populated shells. The system presents a hierarchy both mesoscopically, since there are groups
 907 of nodes more densely connected, and microscopically, since the nodes are distributed on the various shells. The
 908
 909
 910
 911



912 model partially replicates the changes in the maximum
 913 connectivity, but it does not completely reproduce the
 914 empirical hierarchical structure, as the shapes of $n_{(k,m)}$
 915 vs. k are rather different from the empirical ones (insets
 916 of Fig. 9a).

917 Finally, the synthetic hypergraphs generated using the
 918 HADAM model present a rich hierarchical structure that
 919 reproduces quite well the empirical one and its evolution,
 920 both in the maximum connectivity and in the filling pro-
 921 files. Indeed, the memory effect drives the creation of
 922 interactions between nodes that have already met several
 923 times in the past, thus favoring non-trivial patterns with
 924 densely connected groups of nodes. Some quantitative
 925 differences with the empirical structure are still observed,
 926 such as a more progressive emptying of the cores with k ,
 927 and slightly different k_{max}^m values.

928 Figure 9b provides a quantitative comparison of the
 929 hyper-core structures generated by each model with the
 930 empirical one, through the root-mean-square deviation
 931 similarity Σ between the respective hyper-cores filling
 932 profiles in each time window. As expected from the above
 933 considerations, the hyper-core structure of the HADAM
 934 model is the most similar to the empirical one with
 935 $\Sigma \sim 0.95$, followed by the HADA model ($\Sigma \sim 0.80$), and
 936 by the HAD model ($\Sigma \sim 0.60$). Similar results are also
 937 obtained with other similarity measures (see SM).

938 At the mesoscopic scale, the empirical data present a
 939 strong instability in the most central cores (see Fig. 9c),
 940 with a very low similarity $J^*(t, t+1)$ between consecutive
 941 snapshots. The HAD model, on the contrary, presents
 942 a very high stability in the deepest cores, reproducing
 943 the empirical similarity J_N of the entire population, as
 944 expected since the whole population composes the most
 945 central cores (see Fig. 9a). The HADA and the HADAM
 946 models yield a lower stability of the central cores: the
 947 variations in activity and memory effects are enough to
 948 generate changes in the mesoscopic hierarchical structure
 949 and similarities closer to the empirical case, even if still
 950 higher. At the microscopic level, the empirical data set
 951 alternates phases with low and high hypercoreness cor-
 952 relations in consecutive snapshots $\rho^*(t, t+1)$, (see Fig.
 953 9d): during the weekdays the structural position of nodes
 954 change a lot across days (low ρ^*), because of varying ac-
 955 tivities, while during the weekends it is quite stable (high
 956 ρ^*). On the contrary, the three models present approxi-
 957 mately constant correlation values: the HAD model triv-
 958 ially does not present any correlation $\rho^* \sim 0$, since the
 959 model does not generate any hierarchy of nodes in any
 960 time window; the HADA model instead presents higher
 961 correlations $\rho^* \sim 0.30$, as the system generates a hierar-
 962 chical structure with high-activity nodes being the most
 963 central over time; finally, the HADAM model presents the
 964 highest correlations $\rho^* \sim 0.60$, since the memory forces
 965 the creation of correlations in nodes behavior over time
 966 and could be balanced only by strong changes in nodes
 967 activity.

968 These results are further confirmed by comparing the
 969 entire similarity matrices of the models with the ones of
 970 the empirical hypergraph at different scales (see SM, for
 971 the matrices $\Sigma(t, t')$, $J^*(t, t')$, $\rho(t, t')$ and $\rho^*(t, t')$): the
 972 HADAM model better reproduces the evolution and tempo-
 973 ral stability of the empirical system at all the temporal
 974 and structural scales, while the HADA and HAD models

975 feature larger differences, with the HAD model leading
 976 to the widest discrepancy (see SM).

977 We finally compare in Fig. 10 the behaviour of the
 978 time-aggregated centralities measures in the data and
 979 models. The original data set presents a wide variability.
 980 In fact, even if the aggregated hypercoreness W and the
 981 activity-averaged hypercoreness \bar{W} are positively corre-
 982 lated, there are nodes very central on average when ac-
 983 tive (high \bar{W}) but globally not relevant (low W) and vice-
 984 versa. This suggests different node hypercoreness trajec-
 985 tories and node movements across the core structure (see
 986 SM). The system also presents a heterogeneous distribu-
 987 tion of the aggregated hypercoreness W , $P(W)$, which
 988 provides a clear ranking of nodes. Moreover, nodes with
 989 the same snapshot activity a_w can present very different
 990 structural behaviors, indeed the activity is unevenly dis-
 991 tributed in the W classes: the nodes with relevant struc-
 992 tural role (high W) are frequently active (high a_w), but
 993 nodes poorly structurally relevant (low W) can have very
 994 different activity values.

995 In the HAD model all nodes have approximately the
 996 same activity-averaged hypercoreness \bar{W} but different
 997 values of the aggregated one W (see Fig. 10): the HAD
 998 model does not produce any hypercoreness hierarchy of
 999 nodes in any time window, therefore on average when a
 1000 node is active it has the same centrality as the others \bar{W} .
 1001 The aggregated hypercoreness W differentiate among the
 1002 nodes only through their temporal persistence in the sys-
 1003 tem, i.e. through a_w . The distribution of W appears
 1004 homogeneous and peaked.

1005 The HADA model creates a hierarchy of nodes both
 1006 in terms of W and \bar{W} (see Fig. 10): in this case, the
 1007 most globally central nodes are also relevant on average
 1008 when active, while nodes that are less central globally
 1009 can feature different behaviours when active, either be-
 1010 ing very central or not. The distribution $P(W)$ appears
 1011 homogeneous and peaked, with a gradual increase in the
 1012 activity a_w of nodes more relevant. Even if it features
 1013 a hypercoreness hierarchy, the model does not reproduce
 1014 the empirical distribution of the aggregated hypercore-
 1015 ness $P(W)$, and yields a stronger correlation between W
 1016 and a_w than in the empirical data.

1017 The HADAM model yields a hierarchy both in terms
 1018 of W and \bar{W} (see Fig. 10), replicating quite well
 1019 the empirical patterns, even if there are nodes with
 1020 time-aggregated hypercoreness values, W and \bar{W} , higher
 1021 than those empirically observed. The distribution $P(W)$
 1022 is heterogeneous, with few nodes with very high W , and
 1023 also the heterogeneity in nodes structural and temporal
 1024 behaviours is well reproduced, since the distribution of
 1025 a_w in the W classes well replicate the empirical case.

1026
 1027 Overall, these results show how the hyper-core decom-
 1028 position allows to validate the hypergraph models struc-
 1029 turally and temporally at different scales. The three
 1030 temporal models are generated starting from the same
 1031 amount of information extracted from the empirical data
 1032 set and are tuned to replicate the same statistical and
 1033 temporal properties. The HAD model fails to produce
 1034 and replicate the hierarchical structure at any of the
 1035 scales considered, as the model generates a mean-field
 1036 structure without hierarchy. The introduction of attrac-
 1037 tiveness in the HADA model generates a hierarchical

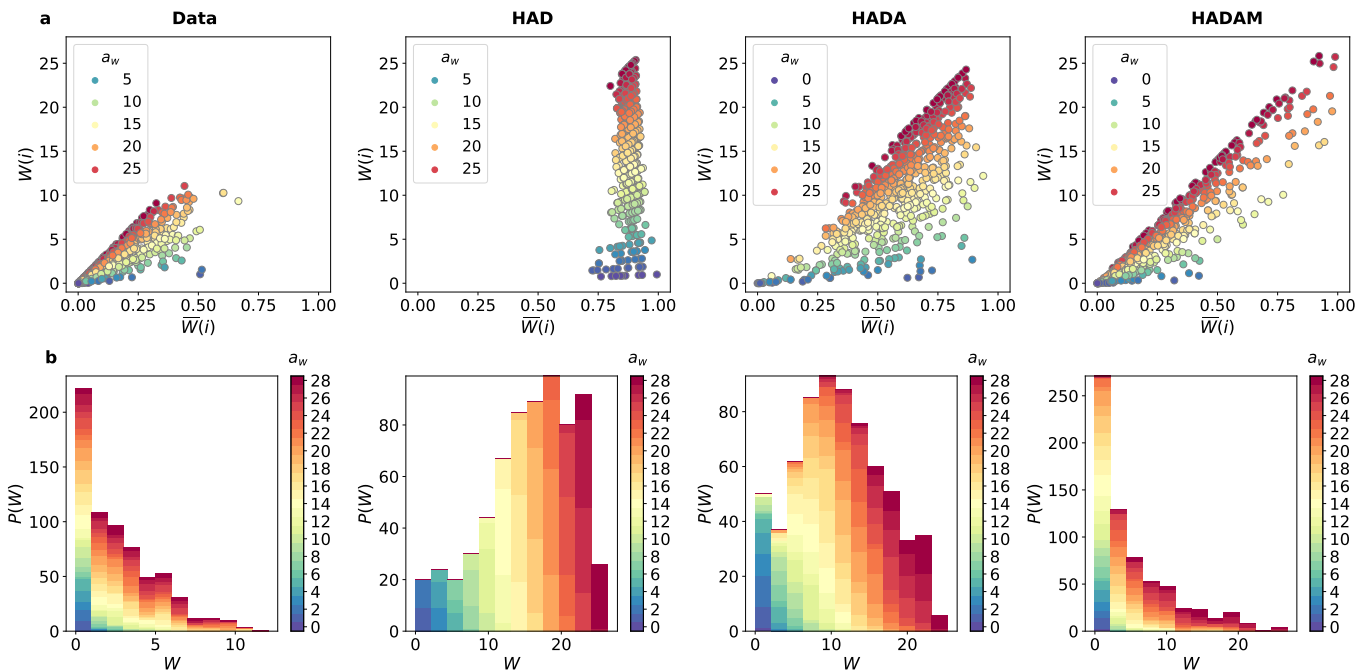


FIG. 10.

1038 structure that however still strongly differs from the
 1039 empirical one, as the model generates a more progressive
 1040 core-periphery structure. The memory effect introduced
 1041 in the HADAM model makes it possible to obtain a hier-
 1042 archical structure that resembles quite well the empirical
 1043 one at all scales, except for a stronger correlation between
 1044 the nodes hypercoreness rankings. Note that analogous
 1045 results can be obtained also considering other data sets
 1046 (see the SM).

1047 III. DISCUSSION

1048 Recently, there has been a recognition of the impor-
 1049 tance of going beyond pairwise and static representations
 1050 for complex systems [5, 15]. In this article, we have put
 1051 forward a method for the structural and dynamic charac-
 1052 terization of temporal hypergraphs, which represent time-
 1053 varying systems involving higher-order interactions. The
 1054 approach is based on decomposing the hypergraph into
 1055 hyper-cores over time, and it provides a multi-scale char-
 1056 acterization: macroscopically, it follows the higher-order
 1057 hierarchical structure over time, monitoring the stabil-
 1058 ity of the overall hyper-core structure; mesoscopically, it
 1059 follows the evolution of specific hyper-cores, observing
 1060 whether stable groups of nodes are densely connected to
 1061 each other or whether they change over time; microscop-
 1062 ically, it follows the structural behavior of single nodes,
 1063 monitoring their movements across the hierarchical struc-
 1064 ture, towards more superficial or more central hyper-
 1065 cores. The approach provides several similarity measures
 1066 that quantitatively estimate the higher-order structural
 1067 stability of the system at different topological scales, also
 1068 identifying temporal patterns in the structure evolution.
 1069 We moreover introduced two time-aggregated centrality
 1070 measures of nodes, by aggregating the instantaneous hy-
 1071 percoreness or by averaging it over the node's activity.

1072 These last measures provide additional information on
 1073 the behavior of the nodes, as opposed to other centrality
 1074 measures that do not account for higher-order structural
 1075 properties.

1076 We applied the method to a wide range of data sets
 1077 describing different systems, characterizing each of them
 1078 and identifying similarities and differences: for example,
 1079 stronger instability characterizes systems where the na-
 1080 ture of the interactions favors variability in the inter-
 1081 action patterns, such as scientific collaborations, confer-
 1082 ences, universities and workplaces; a more stable struc-
 1083 ture is observed instead in systems with patterns of
 1084 repeated interactions due to functional roles, such as
 1085 schools and hospitals. We also linked structural proper-
 1086 ties of nodes to specific roles and activities in the sys-
 1087 tems, thus identifying relevant functions and their evolu-
 1088 tion over time.

1089 The proposed method represents also an effective
 1090 model-validation tool, since it allows to quantitatively
 1091 estimate whether a synthetic temporal hypergraph can
 1092 replicate the structure of an empirical hypergraph and
 1093 its evolution at different topological scales, and to com-
 1094 pare several candidate models. In this direction, we pro-
 1095 posed several models of activity-driven hypergraphs with
 1096 increasing complexity in the mechanisms that drive the
 1097 hyperedges formation and we estimated their structural-
 1098 temporal differences and similarities with respect to the
 1099 empirical systems. We have shown that models taking
 1100 into account solely the node activities and the hyper-
 1101 edges size distribution over time cannot reproduce the
 1102 empirical higher-order structure and its evolution. By
 1103 contrast, introducing attractiveness and memory, while
 1104 keeping the model simple, yields non-trivial hyper-core
 1105 structures and to obtain a behaviour closer to the one
 1106 empirically measured.

1107 Our work opens several research directions and future
 1108 perspectives. It lays the foundations for the development

of new characterization techniques for time-varying hypergraphs [15]: for example, it represents a first step for the definition of a core decomposition of temporal hypergraphs, which is a highly challenging task because of the difficulties in defining a procedure taking into account both non-dyadic interactions and the temporal dimension to generalize e.g. the span-core decomposition of temporal networks [11, 12]. Our work also provides insights for the understanding of higher-order dynamic processes on temporal hypergraphs, since hyper-cores play an important role in dynamic processes [26]: understanding how the multi-scale evolution of the underlying hypergraph affects dynamic processes is of great interest, in order to fully assess the coupling between the dynamics of and on the hypergraph. This is crucial also for the planning of adaptive measures and interventions, e.g. to maximize or prevent the spread of information on a time-varying hypergraph. Finally, our approach provides tools to guide the design of new models for temporal hypergraphs capable of reproducing higher-order structural properties of empirical systems at different topological scales. Here we have proposed examples of activity-driven hypergraphs featuring different interesting properties [9, 13, 39], however more complex models could be devised [35–38, 40], for example introducing correlations between the activity of nodes and the size of hyperedges of which they are member, or considering memory and attractiveness mechanisms involving groups of nodes.

IV. METHODS

A. Hyper-core decomposition

Let us consider an unweighted static hypergraph $\mathcal{H}_t = (\mathcal{V}_t, \mathcal{E}_t)$, composed by the set of its nodes \mathcal{V}_t and by the set of its hyperedges \mathcal{E}_t . A hyperedge $e = \{i_1, i_2, \dots, i_m\} \in \mathcal{E}_t$ consists in a set of m nodes $i_k \in \mathcal{V}_t \forall k = 1, \dots, m$, with $m \in [2, M_t]$, where $M_t = \max_{e \in \mathcal{E}_t} |e|$.

The hyper-core decomposition is a procedure that decomposes the hypergraph \mathcal{H}_t into (k, m) -hyper-cores, i.e., a double hierarchy of nested subhypergraphs of increasing connectivity, provided by hyperedges of increasing size. Specifically, the (k, m) -hyper-core of \mathcal{H}_t , denoted as $\mathcal{F}_t^{(k, m)} = (\mathcal{A}_t^{(k, m)}, \mathcal{S}_t^{(k, m)})$, is defined as the maximum subhypergraph that contains all the nodes $i \in \mathcal{V}_t$ involved in at least k distinct hyperedges of size at least m within the subhypergraph itself. It contains all the hyperedges that are subsets of interactions in the original hypergraph \mathcal{H}_t , of size at least m and that contain only nodes of $\mathcal{A}_t^{(k, m)}$. Therefore, $\mathcal{A}_t^{(k, m)} = \{i \in \mathcal{V}_t \text{ s.t. } D_m^{\mathcal{F}_t^{(k, m)}}(i) \geq k\}$ and $\mathcal{S}_t^{(k, m)} = \{e \cap \mathcal{A}_t^{(k, m)} \text{ s.t. } e \in \mathcal{E}_t \wedge |e \cap \mathcal{A}_t^{(k, m)}| \geq m\}$, where $D_m^{\mathcal{F}_t^{(k, m)}}(i)$ is the number of distinct interactions of size at least m in which the node i is involved in $\mathcal{F}_t^{(k, m)}$. Note that the (k, m) -hyper-core includes the $(k, m+1)$ - and $(k+1, m)$ -hyper-cores, producing a doubly nested hierarchical structure which, by increasing k and m , progressively identifies groups of nodes more densely connected with each other through interactions of increasing order [26]. The (k, m) -hyper-core is obtained by removing progressively and iteratively all the nodes with $D_m < k$ and all the hyperedges of size smaller than m [26].

B. Data description and preprocessing

We consider data sets covering a wide range of interaction systems and present different statistical, topological and temporal properties (see SM).

Scientific collaborations. The American Physical Society (APS) scientific collaborations data set [49, 50] consists in all the APS publications from 1893 to 2021: for each paper the date of publication, the journal and the list of authors are indicated.

We initially addressed some issues appearing in the data: (i) information is missing for some papers, for example on the author list: in these cases we removed the corresponding entries from the data set; (ii) the same author "Name Surname" can appear with the full extended name, as "N. Surname", "N Surname" or "Na. Surname"; analogously with middle names "Name Second Surname" or "Name-Second Surname". To minimize the impact of these inconsistencies, we: (a) identified all entries with the same "Surname"; (b) reassigned the papers associated to dotted names to the corresponding extended name, carrying out the reassignment only in case of uniqueness. Some dotted names do not have or have several extended correspondences, making a unique reassignment impossible: in these cases we consider the contracted name as if it were a unique additional author. See the SM for further details on the size of the various issues. The performed approach reduces the problems related to author identification, but does not completely eliminate the issue: it is still possible that two authors have the same name, therefore the publications are attributed as if they were a single individual. Moreover, in the presence of large collaborations, not all authors are listed [71]. Such issues cannot be eliminated through preprocessing of the data without additional information sources to perform a cross-source analysis [71]. However, even without such additional information, the preprocessed data set gives a good enough picture of the scientific interactions as our purpose is here demonstrative and we do not seek to give precise ranking indications concerning scientists, nor follow in detail some careers.

We thus use the data to build a hypergraph in which each node is an author, a hyperedge represents a paper connecting the co-authors, and it is assigned with a label indicating the corresponding journal. Since we focus on the pattern of collaborations between authors, rather than on the absolute scientific production, we do not take into consideration papers with a single author. We obtain a temporal hypergraph with 1-day resolution, and we focus on 1942-2021. We consider 5-years adjacent time windows and aggregate the temporal hypergraph within each of them, obtaining a sequence of unweighted static hypergraphs. Each static hypergraph is composed of all the nodes and hyperedges active at least once in the considered time window. The same group of authors can have co-authored several papers in the same time window producing fully overlapping hyperedges: in this case we consider only one hyperedge (unweighted hypergraph) and we assign a multiple label to it, including all the journals in which the same group of authors published.

Physical proximity. We consider several data sets of human face-to-face interactions obtained through RFID wearable proximity sensors, made publicly available by

the SocioPatterns collaboration [51, 53, 54] and by the Contacts among Utah’s School-age Population project [58]. These data sets describe interactions between individuals in several settings and cover different time periods: a workplace (InVS15 [52, 53] - 2 weeks), a conference (SFHH [53] - 2 days), a hospital (LH10 [55] - 4 days), two primary-schools (LyonSchool [56], Utah_elem [58] - 2 days) and a high-school (Thiers13 [57] - 1 week). The data consist in each case in lists of time-resolved pairwise interactions between individuals (nodes), i.e., temporal networks with a time resolution of 20 seconds. To identify group interactions and transform such temporal networks into temporal hypergraphs, we carried out the following procedure [23, 26]: (i) pairwise interactions are aggregated over 5-minutes time intervals; (ii) cliques, i.e. fully connected clusters, are identified in each time step; (iii) in each time interval the maximum cliques, i.e. cliques not fully contained in another clique, are identified and promoted to hyperedges. This procedure generates temporal hypergraphs with 5-minutes resolution. Some data sets have moreover node labels providing information on single nodes properties, e.g. class of each student for LyonSchool, Thiers13, Utah_elem, social role for LH10 and working department for InVS15.

We also consider time-resolved data describing physical proximity events between students in a University, collected through the Bluetooth signal of cellphones during 4 weeks within the Copenhagen Network Study [36, 59] (CopNS). The data set provides pairwise interactions between individuals (nodes) with a temporal resolution of 5 minutes and with information on the signal intensity: we perform the preprocessing procedures described in [36], obtaining a temporal hypergraph with 5-minutes resolution.

Email. Finally, we consider a data set describing email communications within an European institution (email-EU [60–62] - 17 months). This data set is publicly available as a temporal hypergraph: each node represents a user, each hyperedge corresponds to an email and involves both the recipients and the sender of the message. The sending time is provided for each hyperedge with 1-second resolution and the information on the directionality of the email is discarded.

C. Labels reshuffling procedures

We implement two reshuffling procedures, one for systems with hyperedge labels (e.g. APS), and one for those with node labels (e.g. LH10).

Hyperedge labels reshuffling. We consider a temporal hypergraph $\mathcal{H} = \{\mathcal{H}_t\}_{t=1}^{t=n}$, in which each hyperedge e is assigned with one or multiple labels. We obtain a reshuffled realization of the temporal hypergraph \mathcal{H}' in the following way: for each static snapshot \mathcal{H}_t , we randomly select two hyperedges e and f of the same size m and, if they have different labels l_e and l_f , we perform a label swap so that e will have the new label $l'_e = l_f$ and f will have the new label $l'_f = l_e$. In the case of hyperedges e with multiple labels $[l_e^1, l_e^2, \dots, l_e^n, \dots, l_e^q]$, one of the labels is randomly selected l_e^n , and the label swap is performed only with it. The procedure is repeated

10^5 times for each size $m \in [2, M_t]$ and for each static snapshot \mathcal{H}_t (if the number of hyperedges of size m is at least 4 and at least two different labels are available). The described procedure preserves in each temporal snapshot the hypergraph structure, the overall number of hyperedges with each label at each order of interaction, while it destroys the correlations between the nodes and the labels of the hyperedges in which they are involved.

Node labels reshuffling. We consider a temporal hypergraph $\mathcal{H} = \{\mathcal{H}_t\}_{t=1}^{t=n}$, in which each node i is assigned with a label l_i . We obtain a reshuffled realization \mathcal{H}' of the temporal hypergraph in the following way: for each temporal snapshot \mathcal{H}_t , we randomly select two nodes i and j and, if they have different labels l_i and l_j , we perform a label swap so that i will have new label $l'_i = l_j$ and j will have new label $l'_j = l_i$. The procedure is repeated 10^4 times for each temporal snapshot. The described procedure preserves the hypergraph structure and the overall number of nodes with a specific label in each temporal snapshot, but it destroys the correlations between the labels of interacting nodes.

D. Temporal hypergraphs models

We generate different synthetic temporal hypergraphs starting from the properties of the empirical hypergraph we want to model. Let us consider an empirical temporal hypergraph \mathcal{H} observed over the time interval $(0, t_{max}]$. We consider $n = t_{max}/\tau$ adjacent time windows $((t-1)\tau, t\tau]$ with $t \in [1, \dots, n]$. Within each of them we extract the set of active nodes (of size N_t), the distribution of the hyperedge size $\Psi_t(m)$, the total number of interactions n_t^{tot} and the total number of interactions in which each node is involved $n_t(i)$. Then we generate synthetic temporal hypergraphs \mathcal{H}' with the same nodes of the empirical hypergraph, that within each temporal window t have the same set of available nodes N_t , the same distribution $\Psi_t(m)$ of the hyperedge sizes of the empirical data and that, by an opportune tuning of the model parameters, reproduce quite well n_t^{tot} and $n_t(i) \forall i$. We consider three different models of temporal hypergraphs. Then, we can perform temporal aggregations for both the empirical $\{\mathcal{H}_t\}_{t=1}^{t=n}$ and each synthetic $\{\mathcal{H}'_t\}_{t=1}^{t=n}$ hypergraphs. For instance, starting from data having a 5-minutes resolution, we generate synthetic hypergraphs with the same temporal resolution, and then we consider hypergraphs aggregated over 1-day time-windows for the analysis.

Activity-driven hypergraph (HAD)

The higher-order activity-driven model (HAD) is the hypergraph generalization of the AD network [13] and of the simplicial activity-driven model (SAD) [9]. In this model, given a population of N nodes, each node is assigned with an activity $a(i)$. In the discrete-time version of this model, in each time-step Δt each node i can activate with probability $a(i)\Delta t$. When a node activates, it generates a hyperedge of size m , drawn from the distribution $\Psi(m)$. The remaining $(m-1)$ nodes participating

in the interaction are selected uniformly at random from the entire remaining population, i.e. each node is selected with probability $1/(N-1)$. At the following time-step all hyperedges are erased and the process continues iteratively. Here moreover, we take into account that the set of available nodes (of size N_t), the hyperedge size distribution $\Psi_t(m)$ and the activity of a node $a_t(i)$ can change over time.

The number of interactions in which a node is involved in the time window t of extension τ is:

$$n_t(i) = a_t(i)\tau + \sum_{j \neq i} a_t(j)\tau \frac{\langle m-1 \rangle_t}{N_t-1}, \quad (6)$$

where the first term is due to the activation of the node i itself and the second term to the activation of another node j . Moreover, $n_t^{tot} = \sum_i a_t(i)\tau$. Therefore, the HAD model replicates the $n_t(i) \forall i$ and n_t^{tot} of the empirical data set by fixing the activity of each node as:

$$a_t(i) = \frac{n_t(i) - \frac{\langle m-1 \rangle_t}{N_t-1} n_t^{tot}}{\tau \left(1 - \frac{\langle m-1 \rangle_t}{N_t-1}\right)}, \quad (7)$$

where N_t , $\Psi_t(m)$, $n_t(i)$ and n_t^{tot} are fixed as in the empirical dataset. We set the time-step Δt equal to the duration of the interactions in the empirical data set.

The model takes into account the hyperedge size distribution, the activity of each single node and their temporal evolution. The mechanism of hyperedges formation is uniform, random and without memory, therefore the generated temporal hypergraph structure is mean-field.

Activity-driven hypergraph with attractiveness (HADA)

The higher-order activity-driven model with attractiveness (HADA) is a generalization of the AD network with attractiveness [39, 69, 70], and it differs from the HAD model through the introduction of an attractiveness parameter which describes the propensity of nodes to attract active interactions. Given a population of N nodes, each node is assigned with an activity $a(i)$ and an attractiveness $b(i)$: in each discrete time-step Δt each node i can activate with probability $a(i)\Delta t$. When a node i activates, it generates a hyperedge of size m , drawn from the distribution $\Psi(m)$. The remaining $(m-1)$ nodes participating in the interaction are randomly selected from the population with probability proportional to their attractiveness, i.e. each node j is selected with probability $b(j)/\sum_{k \neq i} b(k)$. At the following time-step all the hyperedges are destroyed and the process is iterated. For simplicity, hereafter we will assume that $b(i) = a(i) \forall i$, i.e. the most (less) active nodes are also the most (less) attractive ones, as observed in several real systems [69, 70]. The set of available nodes, the hyperedge size distribution and the activity of a node can change over time.

The number of interactions in which a node is involved in the time window t of extension τ is:

$$n_t(i) = a_t(i)\tau + \sum_{j \neq i} a_t(j)\tau \frac{\langle m-1 \rangle_t a_t(i)}{\sum_{k \neq j} a_t(k)}, \quad (8)$$

where the first term is due to the activation of the node itself and the second term to the activation of another

node. The HADA model reproduces the $n_t(i) \forall i$ observed in the empirical data, if the activity is:

$$a_t(i) = \frac{n_t(i)}{\tau \left(1 + \langle m-1 \rangle_t \sum_{j \neq i} \frac{a_t(j)}{n_t^{tot}/\tau - a_t(j)}\right)}, \quad (9)$$

where N_t , $\Psi_t(m)$, $n_t(i)$ and n_t^{tot} are fixed as in the empirical dataset. When $N_t \gg 1$, we can approximate $a_t(i) \sim n_t(i)/\langle m \rangle_t \tau$ since $\sum_{j \neq i} a_t(j) \sim n_t^{tot}/\tau$: this holds for all the time windows of all the datasets considered. We set the time-step Δt equal to the duration of the interactions in the empirical data set.

The model takes into account the hyperedge size distribution and the activity of each node, together with their temporal evolution; the hyperedges formation mechanism is still random and without memory, but favors interactions with high activity nodes. The generated temporal hypergraph has a progressive core-periphery structure: high-activity nodes compose the core, being densely connected to each other and to the rest of the population; nodes with progressively lower activity become gradually more peripheral, being increasingly less connected to each other and only connected to the nodes in the core.

Activity-driven hypergraph with memory (HADAM)

The higher-order activity-driven model with memory differs from the HADA model for the introduction of a memory mechanism, analogous to that introduced in the AD network with memory [67, 68]. Given a population of N nodes, each node is assigned an activity $a(i)$ and an attractiveness $b(i)$: in each discrete time-step Δt each node i can activate with probability $a(i)\Delta t$. Here we consider activities and attractiveness depending on time. At time t moreover, we define the aggregated neighbourhood $\mathcal{N}_t(i)$ of i as the set of nodes i has interacted with in previous time steps. When a node i activates at time t , it generates a hyperedge of size m , drawn from the distribution $\Psi_t(m)$:

- with probability $p_t(i) = 1/(1 + l_t(i))$, the $m-1$ nodes i will interact with are selected among nodes that i has not yet encountered, i.e. who do not belong to its neighbourhood $\mathcal{N}_t(i)$ at time t , where $l_t(i) = |\mathcal{N}_t(i)|$. In this case each node $j \notin \mathcal{N}_t(i)$ is selected with probability $b(j)/\sum_{k \notin \mathcal{N}_t(i)} b(k)$;
- with probability $(1-p_t(i))$, they are selected among nodes that i has already met, i.e. who belongs to its neighbourhood $\mathcal{N}_t(i)$ at time t . In this case each node $j \in \mathcal{N}_t(i)$ is contacted with probability $\omega_{ij}^t b(j)/\sum_{k \in \mathcal{N}_t(i)} \omega_{ik}^t b(k)$, where ω_{ij}^t is the number of times that i and j have participated together in a hyperedge up to time t .

At the following time-step all the hyperedges are erased, the process continues iteratively and correlations are generated over time by the memory. For simplicity, hereafter we use $b_t(i) = a_t(i) \forall i, t$ [69, 70].

In the HADAM model, we cannot determine the activity of the nodes in order to reproduce $n_t(i)$ as observed

1447 in the empirical data, since $n_t(i)$ depends on the full de- 1483
 1448 tailed history of contacts of i up to time t . We fix the
 1449 activities as in the HADA model, with Eq. (9), and we 1484
 1450 have checked that this ansatz reproduces well n_t^{tot} and the
 1451 average total degree in the aggregate snapshots. We set
 1452 the time-step Δt equal to the duration of the interactions 1485
 1453 in the empirical data set.

1454 The model takes into account the hyperedge size distri- 1486
 1455 bution and the activity of each node, together with their
 1456 temporal evolution. Initially, the hypergraph evolves as 1487
 1457 the HADA model since $p(i) \sim 1$ for all nodes. Then $p(i)$ 1488
 1458 decreases and memory effects become relevant: at first an 1489
 1459 active node generates hyperedges with both new and old 1490
 1460 contacts, and then preferentially with only nodes already 1491
 1461 met, selecting those contacted several times in the past. 1492
 1462 This memory-attractiveness mechanism favors dense in- 1493
 1463 teractions between groups of nodes with high activity and 1494
 1464 between groups of nodes that contact each other several 1495
 1465 times, thus generating a rich topological structure. 1496

1466 LIST OF ABBREVIATIONS

1467	APS - American Physical Society	1501
1468		
1469	SM - Supplementary Material	1502
1470		
1471	AD - Activity-driven	1503
1472		
1473	SAD - Simplicial activity-driven model	1504
1474		
1475	HAD - Higher-order activity-driven model	1505
1476		
1477	HADA - Higher-order activity-driven model with	1506
1478	attractiveness	1507
1479		
1480	HADAM - Higher-order activity-driven model with	1508
1481	memory	1509
1482		

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ADDITIONAL MATERIALS

Additional file: Supplementary Material, SM.

DECLARATIONS

Availability of data and materials

The data that support the findings of this study are publicly available. The APS data set can be requested at <https://journals.aps.org/datasets> [49]; the SocioPattern data sets are available at <http://www.sociopatterns.org/> [51–57]; the Contacts among Utah’s School-age Population data set at <https://royalsocietypublishing.org/doi/suppl/10.1098/rsif.2015.0279> [58]; the email communications data set at <https://www.cs.cornell.edu/~arb/data/> [60–62]; the Copenhagen Network Study data set at <https://doi.org/10.6084/m9.figshare.7267433> [59].

Competing interests

1499 The authors declare that they have no competing in-
 1500 terests.

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Authors’ contributions

1506 M.M., I.I., G.P., A.B. designed the study; M.M. per-
 1507 formed the analysis; M.M., I.I., G.P., A.B. analyzed the
 1508 results; M.M. and A.B. wrote the first draft; M.M., I.I.,
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 1633 since here we focus on the characterization of how the el-
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 1635 the singletons are immediately pruned in the hyper-core
 1636 decomposition.
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 1638 centralities [26] by arbitrarily weighing the different hy-
 1639 peredge sizes m in Eq. (1). Here we consider the simplest
 1640 “size-independent” hypercoreness in which all sizes con-
 1641 tribute equally.
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 1643 two hyper-cores filling profiles are identical $a_{(k,m)} =$
 1644 $b_{(k,m)} \forall k \in [1, \bar{K}], \forall m \in [2, \bar{M}]$; the minimum similarity
 1645 $\Sigma = 0$ is obtained when the hypergraphs feature the two
 1646 maximally different configurations, $a_{(1,2)} = 1, a_{(k,m)} = 0$
 1647 otherwise, and $b_{(k,m)} = 1 \forall k \in [1, \bar{K}], \forall m \in [2, \bar{M}]$, i.e.
 1648 in one case the (1, 2)-core contains the entire population
 1649 while all the other hyper-cores are empty, and in the other
 1650 case all the hyper-cores are maximally filled with the en-
 1651 tire population.
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 1653 with different populations, numbers of hyperedges, dis-
 1654 tributions of hyperdegrees $P(D_m^H) \forall m \in [2, M]$ and dis-
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FIGURE LEGENDS

FIG. 1. **Evolution of the hyper-core structure in APS scientific collaborations.** **a:** fraction of nodes $n_{(k,m)}$ in the (k,m) -core as a function of k and m for each 5-years time window. The numbers of active nodes N_t and hyperedges E_t are also reported and the insets show $n_{(k,m)}$ as a function of k for $m = 2$, $m = 6$ and $m = 10$. **b:** root-mean-square deviation similarity $\Sigma(t,t')$ between $n_{(k,m)}(t)$ and $n_{(k,m)}(t')$ (grey diagonal: $\Sigma(t,t) = 1$). **c:** Jaccard similarity $J^*(t,t')$ between the sets of nodes belonging to the most central hyper-cores, i.e. to the (k_{max}^m, m) -cores $\forall m$, at time t and t' (grey diagonal: $J^*(t,t) = 1$). **d:** Pearson correlation coefficient $\rho(t,t')$ between the nodes hypercoreness at times t and t' , considering all the nodes that are active in at least one of the snapshots (grey diagonal: $\rho(t,t) = 1$). **e:** similarity $\Sigma(t,t+1)$ vs. t . **f:** temporal evolution of $J^*(t,t+1)$ and Jaccard similarity $J_N(t,t+1)$ between the entire population in two consecutive time windows. **g:** temporal evolution of the correlation between the nodes hypercoreness in consecutive snapshots, considering all the nodes that are active in at least one of the snapshots, $\rho(t,t+1)$, or only those active in both, $\rho^*(t,t+1)$. Note that macroscopically the size and the density of the interactions evolve in a non-trivial way, however the overall filling of the hyper-cores remains quite similar over time; the composition of the most central hyper-cores is highly unstable, suggesting a high system instability at the mesoscopic and microscopic scales.

FIG. 2. **Hypercoreness evolution for selected nodes in the APS scientific collaborations.** We show the temporal evolution of the hypercoreness $r(i,t)$ for four authors and the mean $\langle r \rangle(t)$ value (average on active nodes): we show the authors I.Y. Lee ($\#_W1$) and R.V.F. Janssens ($\#_W2$), who occupy respectively the first and second position in the ranking produced by the aggregated hypercoreness W over the period 1942-2021, and the authors Guang-Can Guo ($\#_{\bar{h}}1$) and Loren N. Pfeiffer ($\#_{\bar{h}}5$), who occupy respectively the first and fifth position in the ranking produced by the average number of interactions per active windows \bar{h} over the period 1942-2021. Nodes can have different behaviors, ranging from a stable to a bell-shaped temporal profile of the hypercoreness: these profiles mirror movements of the node in the hyper-cores structure towards more central or more superficial hyper-cores, and can reflect the authors' academic trajectories.

FIG. 3. **Time-aggregated hypercoreness in APS scientific collaborations 1942-2021.** **a:** scatter plot of the aggregated hypercoreness $W(i)$ as a function of the snapshot activity $a_w(i)$ for all nodes i , and average aggregated hypercoreness $\langle W \rangle$ as a function of a_w . **b:** aggregated hypercoreness $W(i)$ vs. average number of interactions per active window $\bar{h}(i)$ for all nodes i . **c:** aggregated hypercoreness $W(i)$ as a function of the activity-averaged hypercoreness $\bar{W}(i)$. In all panels the points are colored according to the activity a_w of the corresponding node. Note that the two time-aggregated hypercoreness measures provide complementary information and a complete description of the structural behavior of the nodes over the entire observation period; moreover, they distinguish different behaviors not identified by other centrality measures.

FIG. 4. **Prevalent APS scientific communities in hyper-cores.** **a:** temporal evolution over 5-years time windows of the prevalent journal within each (k, m) -hyper-core of the APS data set, defined as the most frequent hyperedge label in each core (we consider a journal dominant only if its frequency is larger than 0.5; white indicates hyper-cores which are empty or where a dominant journal cannot be defined). **b:** relative frequency P of the various journals within the most central hyper-cores, i.e. (k_{max}^m, m) -cores $\forall m$, and its temporal evolution. **c:** same as **b** for the randomized data. We average the relative frequency over 50 randomized realizations of the hypergraph (see Methods). The error bars give the standard errors. We identify the scientific communities most densely connected at different orders of interaction: this pattern evolves over time, following specific trends of collaborations in the different research areas, and is significant when compared with appropriate randomized systems.

FIG. 5. **Hyper-core structure evolution in daily interactions within a hospital (LH10).** **a:** relative population $n_{(k,m)}$ of the (k, m) -core as a function of k and m for each time window. The number of active nodes N_t and hyperedges E_t is reported for each snapshot. **b:** $n_{(k,m)}$ as a function of k for fixed values of m . **c:** root-mean-square deviation similarity $\Sigma(t, t')$ between $n_{(k,m)}(t)$ and $n_{(k,m)}(t')$ – the grey diagonal corresponds to $\Sigma(t, t) = 1$; **d:** Jaccard similarity $J^*(t, t')$ between the sets of nodes belonging to the most central hyper-cores, i.e. the (k_{max}^m, m) -cores $\forall m$, at time t and t' – the grey diagonal corresponds to $J^*(t, t) = 1$. **e:** Pearson correlation coefficient $\rho(t, t')$ between the nodes hypercoreness at time t and t' , considering all the nodes that are active in at least one of the snapshots – the grey diagonal corresponds to $\rho(t, t) = 1$. **f:** similarity $\Sigma(t, t+1)$ as a function of t . **g:** temporal evolution of both the similarity $J^*(t, t+1)$ and the Jaccard similarity $J_N(t, t+1)$ between the entire population in consecutive time windows. **h:** temporal evolution of the correlation between the nodes hypercoreness in consecutive snapshots, considering all the nodes that are active in at least one of the snapshots, $\rho(t, t+1)$, or that are active in both, $\rho^*(t, t+1)$. Note that macroscopically the density and the size of the interactions are quite stable, even if the overall filling of the hyper-cores changes over time; the composition of the most central hyper-cores is highly stable, suggesting a high system stability at the mesoscopic and microscopic scales.

FIG. 6. **Hypercoreness evolution in the temporal hypergraph of daily interactions within a hospital (LH10).** We show the temporal evolution of the hypercoreness $r(i, t)$ for four agents with different social role: a paramedic (id=1210), a medic (id=1144), a member of the administrative staff (id=1098) and a patient (id=1383). The dashed line shows the mean $\langle r \rangle(t)$ (averaged only on active nodes). Nodes can have different behaviors, ranging from a stable to a non-monotonous temporal profile of hypercoreness. This profile reflects changes in an individual's interaction patterns, corresponding to the node's movements within the hyper-cores structure, either towards more central or more superficial hyper-cores. Note how the patient's hypercoreness is always lower than the average, while the paramedic's hypercoreness is always maximal.

FIG. 7. **Time-aggregated hypercoreness in a hospital (LH10).** **a:** scatter plot of the aggregated hypercoreness $W(i)$ as a function of the snapshot activity $a_w(i)$ for all nodes i , and averaged aggregated hypercoreness $\langle W \rangle$ as a function of a_w . **b:** aggregated hypercoreness $W(i)$ vs. average number of interactions per active window $\bar{h}(i)$ for all nodes i . **c:** aggregated hypercoreness $W(i)$ as a function of the activity-averaged hypercoreness $\bar{W}(i)$. In all panels points are colored according to the node's social role. Note that the two time-aggregated hypercoreness provide a complete and complementary description of the structural behavior of the nodes over the full observation period. Different social roles present different behaviors, e.g., patients present low values of all centrality measures, doctors and administrative staff have heterogeneous behaviors, while nurses feature high values of all centralities.

FIG. 8. **Prevalent social role in hyper-cores of a hospital (LH10).** **a:** temporal evolution over 24-hours time windows of the prevalent social role in each (k, m) -hyper-core of the LH10 data set, defined as the most frequent label in the core: we use a color code for identifying social roles and we consider a role dominant only if its frequency is larger than 0.5. In white are indicated hyper-cores which are empty or where no dominant role can be identified. **b:** temporal evolution of the hypercoreness $r(i, t)$ averaged over all nodes (dashed black line) and averaged over each distinct class. **c:** temporal evolution of the relative frequency P of the various social roles within the top 15% positions of the nodes ranking given by the hypercoreness $r(i, t)$. **d:** same as **b**, but in this case we consider the relative frequency P averaged over 50 randomized realizations of the hypergraph (see Methods). In this case, we also show error bars corresponding to the standard errors. We identify the social roles most densely connected at different orders of interaction. This pattern is very stable, with nurses being the most densely connected at all interaction orders. Nurses present higher hypercoreness than other social roles, while patients have values lower than the average. This pattern is significant when compared to appropriate randomized systems.

FIG. 9. Hyper-cores structure in time-varying hypergraphs models. We consider the CopNS data set as well as the HAD, HADA and HADAM models adjusted to the CopNS node activities and hyperedge size distributions, and aggregated over 1-day time windows. **a:** relative population $n_{(k,m)}$ of the (k,m) -core as a function of k and m from Monday to Thursday of the first week; the number of active nodes N_t and hyperedges E_t are also reported. The insets show $n_{(k,m)}$ as a function of k for fixed values of m . The first row corresponds to the empirical data; the second, third and fourth rows correspond to the hypergraphs generated respectively with the HAD, the HADA and the HADAM models. **b:** similarity Σ between the hyper-cores filling profiles of the empirical hypergraph \mathcal{H}_t and each of the synthetic models \mathcal{H}'_t in the same time window t . **c:** similarity $J^*(t, t+1)$ between the most central hyper-cores, i.e. (k_{max}^m, m) -cores $\forall m$, in two consecutive snapshots, and Jaccard similarity $J_N(t, t+1)$ between the entire population of the data set in consecutive time windows. **d:** Pearson correlation coefficient $\rho^*(t, t+1)$ between the nodes hypercoreness in two consecutive snapshots, considering all the nodes that appear in both time snapshots. In panels **c-d** we consider both the data set and the corresponding synthetic models. The results presented here show that the hyper-core decomposition provides a tool for the validation of temporal hypergraph models: the HADAM model reproduces quite well the empirical hierarchical structure and its evolution at all the topological scales, while the HADA and HAD models fail to reproduce it at all scales.

FIG. 10. Time-aggregated hypercoreness in time-varying hypergraphs models. We consider the CopNS data set with 1-day time windows over four weeks, as well as the three synthetic models. **a:** scatter plots of the aggregated hypercoreness W as a function of the activity-averaged hypercoreness \bar{W} for each node: the points are colored according to the snapshot activity a_w of the corresponding node. **b:** histograms giving the number of nodes $P(W)$ with aggregated hypercoreness W : within each bar we distinguish the relative frequency of nodes belonging to each class a_w , through stacked bars. In all panels, we consider both the empirical hypergraphs (first column) and the corresponding synthetic temporal hypergraphs (second column - HAD, third column - HADA, and fourth column - HADAM). Note that the two time-aggregated hypercoreness provide a description of the structural behavior of the nodes. The distributions of these measures and their correlations help validate synthetic models concerning the structural and temporal properties of single nodes. The HADAM model reproduces the empirical distributions and correlations quite well, while the HADA and HAD models fail to do so.