

# Article Homological landscape of human brain functional sub-circuits

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Abstract: Human whole-brain functional connectivity networks have been shown to exhibit both local/quasilocal (e.g., set of functional sub-circuits induced by node or edge attributes) and nonlocal (e.g., higher-order functional coordination patterns) properties. Nonetheless, the non-local з properties of topological strata induced by local/quasilocal functional sub-circuits has yet to be addressed. To that end, we proposed a homological formalism that enables the quantification of 5 higher-order characteristics of human brain functional sub-circuits. Our results indicated that each 6 homological order uniquely unravels diverse, complementary properties of human brain functional sub-circuits. At the functional sub-circuit level, the rest-task functional dichotomy of default mode 8 network is found to be mostly prominent at the first and second homological scaffolds. Also at such scale, we found that the limbic network plays a significant role in homological reconfiguration 10 across both task- and subject- domain which sheds light to subsequent investigations on the complex 11 neuro-physiological role of such network. Furthermore, at the whole-brain level, rest-task dichotomy 12 was found to be most prominent between rest and different tasks at different homological orders: 13 i) Working memory  $(H_0)$ , ii) Motor task  $(H_1)$ , and iii) Language task  $(H_2)$ . Noticeably, the  $H_1$ 14 homological distance between rest and motor task were observed at both whole-brain and sub-circuit 15 consolidated level which suggested the self-similarity property of human brain functional connectivity 16 unravelled by homological kernel. From a wider perspective, our formalism can be applied, beyond 17 brain connectomics, to study non-localized coordination patterns of localized structures stretching 18 across complex network fibers. 19

Keywords: Functional sub-circuit; Functional Networks, Homological kernel; Topological data analysis 21

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# 1. Introduction

Network science sheds light on complex phenomena - from fake news spreading 23 mechanism in a social network to natural equilibrium in large-scale ecosystems with 24 competing species interactions. Graphs (Networks), despite its convenience and power 25 to unravel many important phenomenon from social, financial to biological networks, 26 lack comprehensive ability to describe higher-order dynamics of complex systems [1]. 27 Indeed, many real-world system, although can be described using diatic relation (edges), 28 have indeed polyadic functionality [2,3]. Prior studies have strongly suggested the critical 29 role of higher-order interactions in terms of explaining complex intertwined dynamics 30 such as phase transitions of emergent phenomena in networked systems [1]. For instance, 31 higher-order effects emerged from neuronal population are shown to be significant in both 32 statistical and topological and domains [2,4,5]. Higher order interactions, as formalized 33 by hyperedges (in hypergraphs) or simplicial complexes (in homology), have shown to 34 unravel many complementary functions, compared to node-/edge-based investigations 35 [1]. 36

The human brain is a complex system exhibiting multi-scale property where inter-37 actions among its finest elements (e.g., neurons) orchestrate emergent phenomenon (e.g., 38 cognition, consciousness [6]). Besides exerting hierarchical cytoarchitecture, human brain 39 functional organizations also display "modular" characteristic - also known as hierarchical 40 modularity [7]. Bullmore and Sporns [8] were among the first investigators noting that 41 whole-brain functional connectivity can be effectively characterized into (functional) mod-42 ules whose elements (e.g., nodes/vertices in a functional connectome (FC)) are contributed 43 by different distributed areas across the cortex. Specifically, the human brain can be de-44 composed into specialized, yet highly interactive functional modules [6,9] (or equivalently, 45 communities in complex networks, see [10-12] among others). The modular setting of 46 human brain into distinctive functional sub-circuits allows its function to adapt flexibly 47 with diverse cognitive requirements [13,14]. Moreover, functional modularity can also 48 explain human brain complexity [6], cognitive reconfiguration [13], rest-task divergence 49 [15], among other functionalities. 50

In 2011, the concept of intrinsic functional connectivity Magnetic Resonance Imaging 51 (fcMRI) network (also known as functional sub-circuits, functional network (FN) or resting-52 state networks (RSNs)) was put forth by Yeo and colleagues [16]. FNs are essentially parallel 53 interdigitated sub-circuits in which each cortical lobe might contain multiple regions 54 belonged to one or more FNs. An a priori set of FNs (or equivalently, functional sub-circuits) 55 elucidates different executive functions of human brain in healthy, neurodegenerative 56 disease or developmental conditions [17]. Mathematically, an *a priori* identification of 57 FNs is a partition of the whole-brain functional connectivity which results in a functional atlas (e.g., a guidance to which brain region(s) belong to which functional sub-circuit(s)). 59 Such partition can be used as a baseline reference to investigate physiological, functional, individual differences of *i*) the same FN across different cognitive conditions [13] or *ii*) 61 different FNs across the same task (e.g., fMRI). Specifically, the mapping of an a priori set 62 of FNs (to different individuals' functional connectivity) allows the investigation of *i*) the 63 functional differences among individuals under different cognitive demands [13,18,19]; ii) 64 aging [18,20,21]; or *iii*) neurological dysfunctions [22–24]. Besides Yeo's functional FN atlas, 65 other highly putative establishments of a priori set of FNs also featured Power et al. [25], Glasser et al. [26], Gordon et al. [27], and most recently Schaefer et al. [28]. The most recent 67 review on the identification and applications of *a priori* set of FN mappings can be found in 68 the work of Bryce and colleagues [17]. 69

In the case of human brain complex networks, higher-order interactions among neuron populations, at the whole-brain level, have been shown to unravel complementary insights that otherwise, would not be fully appreciated by conventional node-based (zeroth-order) or edge-based (first-order) investigations [2,4,5,29,30]. Nonetheless, higher-order characteristics induced from an *a priori* set of FNs has yet been investigated. Understanding complex behaviors arisen at a scale between the microscopic (brain regions) and macroscopic (wholebrain) level would set the stage to a deeper, comprehensive picture understanding of the 76 human brain large-scale functional sub-circuitry, which, in turns, provide foundational 77 support to investigate individualized or task-based parcellations [31,32]. To that end, we 78 formally explored and measured the topological invariant characteristics of an *a priori* set 79 of FNs (e.g., Yeo's sub-circuitry [16]) through the first three homological dimensions:  $H_0$ (connected components),  $H_1$  (first-order (graph-theoretical) cycles), and  $H_2$  (second-order 81 cycles). These explorations on homological properties of FNs are computed on the 100 82 unrelated subjects from the Human Connectome Project (HCP) dataset in which fMRI data 83 were recorded, for each subject, in resting state and seven other fMRI tasks. The fMRI data 84 were processed and parcellated into 360 brain regions, according to [33]. To investigate 85 the higher-order mesoscopic properties of the constructed functional connectomes (FCs), 86 we used the seven *a priori* FNs, proposed by Yeo and colleagues [16], the 14 sub-cortical 87 regions are added for completeness. It is worthy to note that our proposed framework can 88 be applied to other combinations of parcellations and functional sub-circuitry partitions.

# 2. Formalism

The progression to glean topological information for a set of data, which by itself is discrete is first turn it into a graph modeling the first order interactions and then to progress to a topological space by realizing its simplicial clique complex  $\Delta(\Gamma)$  which models simultaneous, and thereby higher order, interactions. The topological construction flow is as follows:

$$X \rightsquigarrow \Gamma \rightsquigarrow |\Delta(\Gamma)|$$

We stress that the first order information yielding the graph is an additional datum, while 91 the clique complex completes this data to a space. The topological space, which is simplicial 92 in nature, has topological invariants associated to it, such as the homology  $H_i(\Delta(\Gamma))$  and 93 Betti numbers  $b_i$ . The 0th Betti number  $b_0$  counts the number of components and the first 94 Betti number  $b_1$  which counts the number of independent loops (i.e. graph-theoretical 95 cycles). If the graph is connected these satisfy  $b_0 - b_1 = \#$  of vertices - # of edges. The next higher interaction is  $b_2$  which counts the number of independent spheres, or more precisely 97 homology classes, in the realization. The realization is given by inserting a simplex for each complete graph, see below. 99

Graphs in this setting are best understood as given by symmetric matrices, the entries of which are given by the first order interaction as witnessed by Pearson correlation functions. Defining a cut–off parameter r for the interactions then determines a graph  $\Gamma(r)$ and the homology becomes a function of this r. Scanning r from 0 to 1 homology is born and annihilated. The sequence of these events is mathematically captured by persistence homology and can be encoded and visualized in terms of bar codes.

When comparing different bar codes, one usually uses the Wasserstein distance, which is a natural norm on the space of such diagram. It is not the only norm though and in special situations other measures are more appropriate.

#### 2.1. Graph, induced subgraph, Clique complex

In the context of this study, the graph (network) quantifying whole-brain functional connectivity profile is called the functional connectome (FC). Induced subgraphs are utilized to model functional sub-circuits (e.g., Yeo's Functional Networks or FNs) of the FC. By construction, an FC (see Appendix for further details on the FC construction) is a complete non-negative weighted graph. The mathematical and computational setup is as follows:

Mathematically, a *graph/network*  $\Gamma$  with vertex set V and edge set of edges E where an edge in E is a two element set  $\{u, v\}$  of vertices. Enumerating the vertex set by  $1, \ldots n$ , a graph is equivalently encoded by its symmetric adjacency matrix  $M(\Gamma)$  whose entries are  $m_{uv} = 1$  if the vertices u and v are connected by an edge and 0 if not. We make the choice that the diagonal entries are 1. A graph is *complete* if there is an edge between any two distinct nodes. The matrix  $M(\Gamma)$  is the the matrix all of whose entries 1. The number of edges of a complete graph is  $|E| = {|V| \choose 2} = \frac{1}{2}(|V||V-1|)$  which is the same as

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the number of non–diagonal independent entries in a symmetric  $|V| \times |V|$  matrix. The two main topological invariants of a graph are the number of connected component  $b_0$  and the number of loops  $b_1 = |E| - |V| + b_0$ , which are also called the first and second Betti numbers the combination  $\chi = b_0 - b_1 = |V| - |E|$  is called the Euler-characteristic of the graph.

A *subgraph* is specified by a subset of nodes and a subset of edges connecting these nodes. Each graph is a subgraph of the complete graph on its vertices. This can be thought of as deleting the missing edges from complete graph or equivalently setting the corresponding matrix entries to 0. An *induced subgraph* is simply specified by a subset of vertices. It contains all the edges connecting these vertices. If V' is the vertex subset the matrix of the induced subgraph is given by the submatrix  $M(\Gamma)_{V'V'}$ . An induced subgraph is a *clique* if it is itself a complete graph, viz. all the entries of  $M(\Gamma)_{V'V'}$  are 1.

To use topological or simplicial methods such as homology, one promotes a graph 134  $\Gamma$  to a simplicial space  $\Delta(\Gamma)$ . This is not simply the graph itself as glued together from 135 points and intervals, but is more involved. It is the realization of the clique complex. The 136 construction can be understood as an iteration of gluing in simplices. A *n* simplex is the 137 topological space of all vectors  $(t_1, \ldots, t_{n+1})$  whose entries are non-negative  $t_i \ge 0$  and 138 whose sum  $t_1 + \cdots + t_{n+1} = 1$ . The dimension, which is the number of free parameters, 139 is *n*. The gluing procedure starts with the 0 simplices. These are the vertices of  $\Gamma$  viewd 140 as point. In the next step one 1-simplex, which is an interval, is glued in for each edge by 141 identifying the endpoints of the interval with the vertices the edge connects. The higher 142 dimensional simplices are glued in according to complete induced subgraphs. For instance, 143 for any three vertices that are pairwise connected by edges, one glues in a 2-simplex, that 144 is a triangle whose sides are the edges. At the next level one glues in 3-simplices, that is 145 tetrahedra, for each complete graph on 4 verities, which has 6 edges identifying the 4 sides 146 of the tetrahedron with the triangles corresponding to the three edge subsets and so on. The 147 gluing procedure is tantamount to giving the (semi)-simplicial structure which specifies to 148 what the *n* dimension n - 1 boundary simplices of an *n* simplex are glued, in such a way 149 that the gluing is consistent with all sub–simplices, regardless of their dimension. 150

The complete graph on *n* vertices as space realizes to the full *n* simplex. Given an 151 arbitrary graph the realization of the clique complex has such a simplex for each complete 152 induced subgraph and these simplices are glued together by inclusion of subgraphs. This 153 identifies the simplex of a subgraph of a complete graph as a side of the simplex of the 154 graph and hence the space is glued together from maximal simplices corresponding to 155 maximal complete subgraphs along faces corresponding to common subgraphs. One can 156 iteratively construct this space by gluing in higher and higher simplices. This space is 157 higher dimensional and has more topologicial invariants, the higher Betti numbers  $b_i$ 158 which are the dimensions or ranks of the respective homology groups  $H_i$ . The number of 159 connected components is the same for the graph and the associated space. The first Betti number  $b_1$  may differ depending on whether one is looking at the graph or the space. The 161 first graph Betti number for the complete graph is  $\frac{1}{2}(|V|(|V|-3)+1)$  while the first Betti 162 number of the corresponding space, the simplex, is 0. 163

#### 2.2. Filtration by weights and persistent homology

**Preface.** A *non-negatively weighted graph* is a graph together with a weight function  $w : E \rightarrow 105$ [0,1] on its edges. Again, after enumerating the vertices this defines a symmetric matrix 166  $W = W(\Gamma, w)$  with entries  $w_{uv} = w(\{u, v\})$ , i.e. the weight of the edge connecting u and v. 167 If there is no such edge the entry is 0, and the diagonal entries are fixed to be 1. Choosing 168 a cut-off r defines the symmetric matrix W(r) whose entry  $w(r)_{uv} = 1$  if  $w_{uv} \ge r$  and 0 169 if  $w_{uv} < r$ . It has 1's on the diagonal and defines the graph  $\Gamma(r)$ . Note that  $\Gamma(0)$  is the 170 original graph and  $\Gamma(1)$  is the graph on the vertex set with no edges. Let  $\overline{W}$  be the order set 171

containing unique weight values, in decreasing order, in matrix W, varying the threshold parameter r from 0 to 1, defines a sequence of subgraphs as follows: 173

$$\Gamma(1) \subset \Gamma_1 = \Gamma(r_1) \subset \Gamma_2 = \Gamma(r_2) \subset \dots \subset \Gamma_{\bar{W}} = \Gamma(r_{|\bar{W}|}) \subset \Gamma = \Gamma(0).$$
(1)

with  $1 > r_1 \cdots > r_{|\bar{W}|} > 0$  and the  $\Gamma_j$  are the finitely many different graphs that appear. At each stage j some edges are added from the lower stage j - 1. The graph  $\Gamma(1)$  is the subgraph with full vertex set, whose edges are given by the non–diagonal entries 1. In practice, if the weights are Pearson correlations functions, the only entries of 1 will be along the diagonal and the graph  $\Gamma(1)$  is simply the discrete set of data.

Note that since set *W* describes diatic **functional couplings** (e.g., similarity) between two nodes of a network (or brain regions of interest (ROIs) in this formalism), it implies that the "distance" (e.g., dissimilarity) between two nodes is defined as follows:

$$d_{uv} = 1 - w_{uv}$$

In other words, with this set up, we ensure that

- $\Gamma_1$  is essential the 1-skeleton scaffold where all nodes are perfectly coupled ( $d_{uv} = 0$ ), which results in an empty graph.
- $\Gamma_{j_1}$  is always an induced subgraph of  $\Gamma_{j_2}$  for all  $j_1 < j_2 \le |\bar{W}|$ ;
- The sequence  $\{\Gamma_l \mid l \in [\bar{W}]\}$  starts with an empty graph (homeomorphic to  $\mathbb{Z}_n$ ) and ends with a complete graph (or a clique of *n* nodes) (homeomorphic to simplicial complex of size *n*, i.e.  $K_n$ ).

Given a filtered system, that is a sequence of inclusions of spaces as (1), one can utilize the 189 tool of persistence homology to track the changes of the fundamental topological invariants 190 of homology and Betti-numbers. This supplies a characteristic for the whole sequence. 191 We wish to stress that it is the sequence that is of importance here. The two endpoints 192 have rather trivial topological properties. If the start is just the data, then this is a discrete 193 set, and at the other end the space is just a full simplex corresponding to the complete 194 graph, which is contractible. The transition from one to the other and the appearance —and 195 disappearance— of higher homology is what is kept track of by persistent homology. 196

Bar codes and distances between them. The fingerprint is the variation which is quantified 197 by the bar codes. The variation parameter is the parameter *r* introduced above. A bar code 198 is a type of signature for the variation. For each persistent homology class it records the 199 value of the parameter  $r_{ini}$  when a representative appears (birth) and the value  $r_{fin}$  when 200 it disappears (death). This is an interval (or bar)  $[b(c) = r_{int}, d_{c}c) = r_{fin}]$ . At any given 201 r the homology is given by those classes c for which  $r \in [b(c), d(c)]$ . In the variation all 202 higher homology classes are born and eventually die. The 0-th homology starts with as 203 many classes as data points and then eventually decreases (classes die) until there is only 204 one class left, which says that space is connected. The bar code is equivalently encoded by 205 the persistence diagram which the set with multiplicity (multiset) of all the endpoints of the bars  $\{(b(c), d(c))\}$ . This is actually a multi–set, since some of the classes may appear 207 and die at the same parameter values and these multiplicities are recorded, e.g. (.2, .8) with 208 multiplicity 2 means that there are two bars of this type. Its *p*-th part  $Dgm_{p}$ , is given by 209 bar corresponding to classes of homological dimension *p*.

**Topological distance formulation.** The Wasserstein distance is the natural norm on the<br/>diagram space, e.g. the birth-death diagram of topological features. The Wasserstein<br/>distance is the right measure for processes taking one diagram to another in a varying<br/>family —now of persistence diagrams. This is well suited for analyzing a basic underlying<br/>setup with variations. This is commonly viewed and addressed as the stability theorem. In<br/>the case under study these are that are induced by individuation or specific tasks. in the<br/>case at hand. We use Wasserstein distance to compute the distance between two diagrams211

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for the first and second order homology (e.g., p = 1, 2) in various scenarios (e.g., comparing topological behaviors between the same functional networks at resting condition).

Specifically, for a fixed homological order *p* (in this paper, p = 1, 2), the *q*-Wasserstein 220 distance  $D_{W,q}$  ( $\forall q > 1$ ) for two persistent diagrams  $Dgm_p(X)$  and  $Dgm_p(Y)$  for two data 221 sets X, Y can be defined as follows [34]. For a single interval I = [x, y] set  $dd(I) = \frac{1}{2}(y - x)$ 222 which is the distance to the diagonal of the point (x, y) in  $\mathbb{R}^2$ . For two intervals I =223  $[x_1, y_1], I = [y_1, y_2]$  define their distance as  $d(I, I) = \max(|x_2 - x_1|, |y_2 - y_1|)$ . This is the 224 max norm distance for the two points  $(x_1, y_1), (x_2, y_2)$  in  $\mathbb{R}^2$ . A partial pairings between two 225 sets *S* and *T* is a choice of subsets  $S_0 \subset S$ ,  $T_0 \subset T$  and a 1-1 correspondence between the two 226 subsets  $\pi$  :  $S_0 \iff T_0$ . This extends to sets with multiplicity by choosing multiplicities of 227 elements and matching them with multiplicity. Given diagrams  $Dgm_{\nu}(X), Dgm_{\nu}(Y)$  let  $\Pi$ 228 be the set of all partial pairings then. The Wasserstein distance minimizes the sum of three 229 contributions: the distances between intervals that are paired and two contributions of the 230 distance to the diagonal for intervals that are not paired. It minimizes over two possible 231 scenarios, points moving and points moving in and out of the diagonal. The first means 232 that the classes shift in their rates and the second means that the classes vanish from the 233 diagram and new classes are introduced. Given  $\pi$  let  $Dgm_p(X)_1 = Dgm_p(X) \setminus Dgm_p(X)_0$ 234 and  $Dgm_p(Y) = Dgm_p(Y) \setminus Dgm_p(Y)_0)^q$  be the complements. 235

$$D_{W,q}(Dgm_p(X), Dgm_p(Y))) = \min_{\pi \in \Pi} \left[\sum_{I \in Dgm_p(X)_0} d(I, \pi(I))^q + \sum_{I \in Dgm_p(X)_1} d(I)^q + \sum_{J \in Dgm_p(Y)_1} d(J)\right]^q\right]^{\frac{1}{q}}$$

In the zeroth order homology the Wasserstein distance becomes an unnatural choice. <sup>236</sup> This is due to the fact that the data points are the 0–classes and they are all born at r = 0. <sup>237</sup> Thus a contribution as disappearing or appearing from the diagonal which signifies being <sup>238</sup> born at different times is not a possible scenario. <sup>239</sup>

It is better to consider  $Dgm_0(X)$  just as the multiset of endpoints of the bars [0, d(x)] where  $x \in X$  and use the classical Hausdorff distance to measure the (dis-)similarity between two point clouds living in  $\mathbb{R}$ . This specialized to:

$$D_H(Dgm_0(X), Dgm_0(Y)) = \max_{x \in X} \min_{y \in Y} |d(x) - d(y)|, \max_{y \in Y} \min_{x \in X} |d(x) - d(y)|$$

#### 2.3. Functional connectomes and mesoscopic structures

Mesoscopic structures are typically referred to structures whose elements are proper subsets of system's elements. In brain connectomics domain, there are two types of mesoscopic structures: localized/quasilocalized and non-localized (topological strata). In this section, we provide a overview and definition of each type in the context of brain connectivity.

# 2.3.1. Localized mesoscopic structures

Localized mesoscopic structures are sub-systems that learned from local network properties such as nodes or edges, or correlations among neighboring nodes. In brain connectomics, these sub-structures are induced from a wide arrays of techniques, including but not limited to clustering [16,25], low dimensional approximation of high-dimensional dynamics [35–39]. The most commonly known localized mesoscopic structures in brain networks are often referred to as functional sub-circuits or functional networks [9].

**Definition 1.** (Definition adapted from [40]) An a priori set of Functional networks (FNs) are sub-circuits (or equivalently, sub-networks) that are highly-reproducible across individuals at resting condition (absence of task-induced cognitive demand). Hence, FNs are also known as Resting-State networks (RSNs).

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**Figure 1. Topological landscape of human brain functional networks: Panel A** is the schematic representation of a graph (e.g., functional connectome) modeling first-order interactions (e.g., functional couplings) with weight values  $w_{uv} = d_1, d_2, e, b_2, b_1$ . **Panel B** is a sequence of induced subgraph scaffolds (also referred to as filtration) by scanning across  $w_{uv}$  (Note that the filtration is built on  $d_{uv} = 1 - w_{uv}$ ); hence, the starting point  $\Gamma(w_{max} = 1) = \Gamma_1$  is an empty graph. **Panel C** represents the super-graph construction by merging all ROIs belong to the same FN to one super-node through equivalence relation  $\overline{\Gamma} = \Gamma/\gamma$  which is defined as follows:  $\gamma_1 = 1$  (e.g., FN1);  $\gamma_2 = 2, 3, 4, 5, 6$  (e.g., FN2) and  $\gamma_3 = 7, 8, 9, 10$  (e.g., FN3). Notice that the super-graph itself is a graph; hence, homological computations that were applied in the original graph can also be applied to the super-graph itself. In this example, the super-/consolidated graph has 3 super-nodes. Additionally, the weight matrix is re-scaled according to  $\overline{w}_{i,j}$ . **Panel D** is the corresponding persistent diagram for the first homology which accounts for two first-order cycles in a network: (2,3,4,5,6) and (7,8,10,9); here, we see that cycle (2,3,4,5,6) lasts longer (more persistent) compared to cycle (7,8,10,9). Finally, when scanning across five distinct *r* parameters, we obtain the zeroth and first Betti numbers:  $b_0 = 10, 6, 3, 3, 3, 1$  and  $b_1 = 0, 1, 2, 1, 0, 0$ , respectively.

Special collections of induced subgraphs are used to group brain regions of interest (ROIs) 260 into localized/quasilocalized mesoscopic structures of brain functions denoted as func-261 tional sub-circuits or equivalently, functional networks (FNs). A collection of k subgraphs 262 (of graph  $\Gamma$ ) is denoted as  $\{\gamma_i \subset \Gamma \mid i \in [k]\}$ . A collection of induced subgraphs is *a vertex* 263 *covering* if the graphs each vertex of  $\Gamma$  is a vertex of one of the  $\gamma_i$ . Such a vertex covering is 264 disjoint if the  $\gamma_i$  have disjoint vertices. After enumerating all nodes by  $1, \ldots, n = |V|$  the 265 collection of induced subgraphs is fixed by the membership assignment. This is specified 266 by a partition vector denoted as  $\sigma \in [k]^n$  where  $\sigma = [\sigma_u] = i \in [k]$  indicating that *u* belongs 267 to  $\gamma_i \mid i = \{1, 2, ..., k\}$ . Note that in network science, FNs are equivalent to the term "com-268 munities" [10–12,41]. The problem of identifying the set of communities  $\{\gamma_i \subset \Gamma \mid i \in [k]\}$ 269 for a given complex network is called the community detection problem [10-12,41,42]. 270

While studies of network properties and dynamics using locally featured properties 272 (nodes, edges attributes) provided a well-grounded approach, these methods were proven to be cumbersome in describing and quantifying heterogeneity existing across network 274 dynamical fabrics. These structures usually encompass many-body interactions or en-275 capsulate topological sub-structures that can not be mathematically described using local 276 attributes. To that end, homology [43] offers a unique capability to capture the so-called 277 non-localized mesoscopic structures that otherwise, cannot be reduced to local or quasilocal 278 network properties. In the context of weighted complex networks, persistent homology is 279 used to identify how long (the persistence of) a hole (at any given dimension) lasts from its 280 birth (the weight scale  $w_B^* \in [0, 1]$  that the hole is observed) to its death (the weight scale 281  $w_D^* \in [0, 1]$  that the hole is filled). 282

In the context of functional brain connectivity, non-localized mesoscopic structures 283 in a FC represent the encapsulated area where there is *less* functional connectivity collec-284 tively formed among brain regions encapsulating these structures [44]. Such structure 285 characterizes the notion of hole; the boundary that wraps around these structures are the 286 non-localized mesoscopic fabrics characterized by the so-called cycles. These cycles exist in 287 different homological dimensions for a given networked system which can be described 288 in the language of a manifold. The hollow structures (holes) could be seen as overarching 289 wraps-around special hollow structures in a manifold with different characteristics and properties, compared to functional networks [16,45–47] or communities [10,11,41,48] in 291 complex networks. 292

#### 2.4. Consolidated/Super graph

The system under consideration is naturally regarded as a two-level system given by 294 the ROIs and their connections. The first level is made up of the individual ROIs and the 295 second level is given by the connections between the ROIs. In graph theoretical language, 296 the full graph  $\Gamma(r)$  containing all the nodes naturally has a subgraph  $\gamma_i(r) \subset \Gamma(r)$ . These 297 subgraphs form a supergraph, which has the subgraph as new vertices and has the edges 298 between two vertices if there are edges between the subgraphs. There are two versions, 299 the first is the multi-edged graph that is described graph theoretically by contracting 300 all the edges of the subgraphs  $\gamma_i$  that is if  $\gamma = \bigcup_i \gamma_i$  is the union of subgraphs, then 301  $\overline{\Gamma} = \Gamma/\gamma$ . Reducing possible multiple edges to just one edge on has the reduced graph 302  $\overline{\Gamma}^{red}$  which is again an ordinary graph described by a matrix. For a weighted graph, 303 assuming the subgraphs are not connected, the graphs  $\gamma_i$  correspond to block matrices 304 along the diagonal and the edges of the quotient graph are the off block entries. To 305 obtain a matrix one can consolidate the weights into one weight by choosing a function 306  $W_{i,j} = f(w_{u_k,v_l}), w_{u_1,v_2}, \ldots, w_{u_1,v_k}, w_{u_2,v_1}, \ldots, w_{u_l,v_k}$  where  $u_1, \ldots, u_l$  are the vertices of  $\gamma_i$  and 307  $v_1, \ldots, v_l$  ar the vertices of  $\gamma_i$ . One such choice is  $W_{i,j} = \sum_{u \in \gamma_i, v \in \gamma_i} w_{u,v}$  and then normalize 308 to 309

$$\bar{w}_{i,i} = W_{i,i} / max(W_{i,i})$$

In the case under consideration the graph  $\overline{\Gamma}$  has eight (super-)vertices corresponding to each FNs. The basic topological invariant of the loop number is of great interest as it is a measure of the inter-connectivity of these "super-regions". The persistent homology for the normalized super graph, that is the consolidated graph, will then complement this information to show clusters of correlations between FNs. 310

#### 3. Results

3.1. Data

**Human Connectome Project (HCP) Dataset**. We used the master data release extracted from the HCP Young Adult (HCP-YA) subject release [49]. Specifically, the fMRI dataset is obtained from HCP depository (http://www.humanconnectome.org/), with Released Q3. In general, all MRI neuroimaging modalities were acquired in two different days, with two

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different scanning patterns (e.g., phase acquisitions: left to right or LR and right-to-left or RL). Detailed description is in the next section and **Figure 2**.

**Figure 2. fMRI whole-brain connectome multi-level analysis workflow.** For each task, we started with individual level functional connectome. On the global (macroscopic) level, we have individual analysis as well as group-averaged analysis, and the functional network (mesoscopic) level extracts functional networks from either the individual or group-averaged macroscopic graph. The consolidated graph is constructed by aggregating the nodes from the group-averaged macroscopic level connectome.

HCP Functional Data. The fMRI data from the 100 unrelated subjects in the HCP Q3 323 release were employed in this study [49,50]. Following the HCP protocol, all subjects had 324 provided written consent to the HCP consortium. The two resting-state functional MRI 325 acquisitions with HCP filenames: *rfMRI\_REST*<sub>1</sub> and *rfMRI\_REST*<sub>2</sub> were collected in two 326 separate sessions (on two different days), with two distinct scanning acquisitions (LR and 327 RL) for each day, see [33], [49], and [50] for further details. Besides resting state, the dataset 328 also includes fMRI data from seven (07) fMRI tasks: gambling (*tfMRI GAMBLING*), rela-329 tional or reasoning (*tfMRI\_RELATIONAL*), social (*tfMRI\_SOCIAL*), working memory 330 (*tfMRI\_WM*), motor (*tfMRI\_MOTOR*), language (*tfMRI\_LANGUAGE*), and emotion 331 (*tfMRI\_EMOTION*). Per [33], [51], three following fMRI tasks were obtained on the first 332 day: working memory, motor, and gambling; the rest were obtained on the second day. 333 The local Institutional Review Board at Washington University in St. Louis (scan site) 334 approves all the scanning protocol used during the HCP dataset acquisition process used 335 in this paper. Please refer to [33,51,52] for further detailed description on the HCP-YA 336 dataset. Note that all tasks and resting functional MRIs are treated with equal importance. 337 In this work, we denote seven fMRI tasks as gambling (GAM), relational (REL), social 338 (SOC), working memory (WM), language processing (LANG), emotion (EMOT), and motor 339 (MOT). 340

Table 1 depicts basic information about fMRI conditions' run time and the number of341time points for each task. Subsequently, along with table 1, brief description of each fMRI342condition is provided below. An extended description is provided in HCP manual<sup>1</sup>.343

<sup>1</sup> https://www.humanconnectome.org/storage/app/media/documentation/s1200/HCP\_S1200\_Release\_ Reference\_Manual.pdf.

fMRI Conditions	Run time (min:sec)	# of time points
REST1 (& REST2)	14:33	1200
EMOTION (EMOT)	2:16	176
GAMBLING (GAM)	3:12	253
MOTOR (MOT)	3:34	284
LANGUAGE (LANG)	3:57	316
RELATIONAL (REL)	2:56	232
SOCIAL (SOC)	3:27	274
WORKING MEMORY (WM)	5:01	405

**Table 1. fMRI task scanning length and number of frames description.** All fMRI task run times were reported in order of minutes and seconds. Except for resting state (for which, each subject were scanned twice per day for a total of  $2 \times 2 = 4$  sessions), all other tasks have two scans (RL and LR). TR is time between two consecutive readings.

- REST: Eye open with relaxed fixation on a bright cross-hair with dark background.
  1200 time points were obtained with 720 ms TR.
- EMOTION: Subject was instructed to match two faces (or shapes) are shown at the bottom to the top of the screen. Faces are shown with angry/fearful expression. Each scan involves 3 face blocks and 3 shape blocks with 8 seconds of fixation.
- GAMBLING: card playing game where subject needed to guess a number of a card in order to win or lose money. At each trial, subject was instructed to guess whether a card has value larger or smaller than 5, given the numerical range of the cards was between 1 and 9. Subjects had 1.5 second to respond and 1 second of feedback.
- LANGUAGE: At each scan, four blocks of story tasks and four blocks of math task were presented to the subject. Stories contained brief auditory information followed by choice of questions about the story topics. Math tasks contained arithmetic questions with a similar level of difficulty compared to the story task.
- 5. MOTOR: subjects were shown various cues and instructed to either tap (left and right) fingers, squeeze (left or right) toes, or move tongue in response to different areas of human brain motor cortex. The task contains a total of 10 movements (12 seconds per movement), preceded by a 3 second cue.
- RELATIONAL: subject were presented 6 shapes along with 6 different textures. Given two pairs of objects (one on the top and the other one at the bottom of the screen), the subject had to decide whether the shape (or texture) differed across the pair on the top screen. In addition, they had to decide whether the same difference got carried over the bottom pair.
- SOCIAL: subjects are shown a 20 second video clip containing randomly move objects of various geometrical shapes (squares, circles, triangle etc.). After that, the subject was instruct to response whether these objects has any mental interactions (shapes took into account feelings, thoughts), Undecided, or No Interactions.
- WORKING MEMORY: subject was presented with trials of tools, faces, body parts.
  Four different stimulus types were presented in each run. In addition, at each run,
  two types of memory tasks were presented: two-back and zero-back memory task.

**Brain atlas**. The brain atlas used in this work based on the cortical parcellation of 360 brain regions proposed by Glasser and colleagues [26]. Similarly to description in [13,53,54], 14 sub-cortical regions were added for completeness, as provided by the HCP release (filename *Atlas\_ROI2.nii.gz*). We accomplish this by converting this file from NIFTI to CIFTI format, using the HCP workbench software<sup>2</sup> through the command -cifti- create-label. We then obtained a brain atlas of 374 brain regions (360 cortical + 14 sub-cortical nodes) registered 376

<sup>&</sup>lt;sup>2</sup> http://www.humanconnectome.org/software/connectomeworkbench.html

to a common space which allowed us to parcellate fMRI voxel-level BOLD time series into brain region of interest level time series (command: -cifti-parcellate). Time series were z-scored by using command -cifti-math. 381

**Estimation of functional connectomes**. Parcellated time-series were then used to construct the whole-brain functional connectivity by computing the Pearson's correlation coefficients for each pair of brain regions. This operation can be completed using *Matlab* command -corr which results in a symmetric matrix. All entries in the whole-brain FCs were applied the absolute values so that the threshold parameter r = [0, 1].

The mapping of functional networks onto FCs. After each subject is registered to the 387 appropriate common space and properly parcellated according to Glasser's parcellation, 388 we explore the topological features of human brain functional connectivity (FC) by further 380 subdividing whole-brain FC into Resting State Networks (equivalently referred to as 390 functional networks/communities), see [16]. This particular partition includes seven 391 functional networks (FNs): Visual (VIS), SomatoMotor (SM), Dorsal Attention (DA), Ventral 392 Attention (VA), Limbic (LIM), Frontoparietal (FP), Default Mode Network (DMN); Sub-393 cortical (SUBC) region is, as mentioned above, added into this atlas for completeness. 394 Consequently, the parcellation comprised of eight (8) FNs for each subject/task. 395

#### 3.2. Group analysis: Macroscopic whole-brain Level

**Topological differences between rest and fMRI tasks**. We first explore the topological 397 distances at the group-average whole-brain connectivity level between resting state and 398 fMRI task activation states (see **Figure 3**, see **Figure ??** for the persistent diagram at the 399 macroscopic level). Each homological group consists of three figures, the first one is the 400 bottom left heatmap, representing the pair-wise Wasserstein distance. The bottom right 401 bar plots show the average distance between one task to all other tasks, thus the task 402 with the highest average distance will indicate its high differentiation with other tasks. 403 Finally, the top right plot shows the variance of each task looking at their distance from 404 the other tasks. Specifically, the zeroth homology suggests that the relational task is the 405 most different to the emotion task. Indeed, other studies, such as [13] through network 406 morphospace mechanism, have also suggested that relational and emotion tasks activate 407 minimally-to-none overlapping functional circuits of the human brain. In terms of  $H_0$  (i.e. 408 connected components), relational task is also the most distinctive task, compared with 409 others (highest average); relational task is followed by resting state on average difference 410 with other tasks. Moreover (see Figure 3B), the first homology exhibits the highest degree 411 of differentiation between resting state and task-positive state, as measured by average 412 first homological Wasserstein distance between rest and task bar codes. The first homology 413 also suggests that the motor task is the most topologically different task, compared to the 414 resting state. This finding was consistent with current literature (e.g., Amico and colleague 415 [15]) which stated that motor task exhibited the most distant "within-functional network" 416 edges, relative to other fMRI tasks in the HCP dataset. This result also suggests that at a 417 global scale, the motor cortex whose brain regions are largely employed by motor task, 418 modulates increasing functional activities through forming global transduction pathways 419 with "loop-like" feedbacks (e.g., first-order cycles).

#### *3.3. Group analysis: Consolidated graph* $\overline{\Gamma} = \Gamma / \gamma$

With the construction of consolidated graphs, we generated a smaller-scale representation of the brain connectome to 8 super nodes, which includes 7 Yeo functional networks and one node for subcortical regions. Here, the super-graph is constructed using the equivalence relation at the node level. As such:  $\overline{\Gamma} = \Gamma/\gamma$  such that  $\gamma = u \sim v \mid \sigma_u = \sigma_v, \forall u, v \in V$ . In other words, all brain ROIs belong to the same functional network are contractible.

Since the graph is much smaller, no birth was detected for a 2D simplicial complex in the filtration process, thus only zeroth and first homology were included in the analysis (see Figure 4, see Figure ?? for the persistent diagram at the consolidated level). In the

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**Figure 3. Group-Average Macroscopic Homological distances between fMRI tasks and rest.** Specifically, three panels (e.g., left, middle, and right) represent the zeroth (**Panel A**), first (**Panel B**), and second (**Panel C**), respectively homological distance between fMRI tasks and resting condition. Group-average FCs are computed by taking the average of all subjects in the 100 unrelated subjects dataset sampled from the HCP project. The zeroth homological distance is computed using the Hausdorff formula (measured between persistent diagrams of two FNs extracted from group average FC) while the first and second homology distances are computed using the Wasserstein formula. In each panel, the left triangular heatmap represents the distance; the bar plots represent the average distance; and the circular plots represent the variance among fMRI tasks.

consolidated setting, we found that the social-resting task pair has the highest distance with 430 the zeroth homology, indicating that in the Yeo functional network level, the connectivity 431 representation captured more differences in social task and resting states (see Figure 4A). 432 By the nature of zeroth homology, where we are looking at connected components, the 433 different most-distinct task pair between the global level and consolidated level indicates 434 the choice of representation could impact the topological configuration in brain connectivity. 435 However, the Wasserstein distance between different tasks in the first homology revealed 436 topological invariant among both the global scale as well as node-aggregation scale as 437 the resting state and motor task pair also have the highest distance measure (see **Figure** 438 4B). This consistency validated the robustness of the first persistent homology class in 439 disentangling the brain's functional circuits. In addition to the consistency in the most 440 distinct task pair, the resting state task also consistently appear as the most differentiated 441 task compared to other tasks based on the average distance for each task [55,56]. This 442 indicates that there is a significant reorganization in brain connectivity when people engage 443 in activities from a resting state. Especially for motor tasks, it engages more different brain 444 regions than other tasks, and thus it is also the second distinct task as it is the task that 445 requires responses involving movement.

#### 3.4. Group analysis: Functional network (mesoscopic) Level

In previous sections, we calculated the Wasserstein distance between different tasks, 448 where all of the nodes in the brain connectome were included. In order to assess for a given task, how the brain connectivity shifts from one functional network to another, we 450 also conducted mesoscopic level analysis by extracting the 8 functional networks from the 451 group-averaged global graph. Since previous discoveries showed that the resting state 452 task involves brain regions that are most distinct from other tasks, and the Yeo functional 453 network was also optimized on the resting state fMRI, we focused our analysis on the 454 distance between functional networks in the resting state task and the mesoscopic level 455 topological configuration (see Figure ?? - ?? for the analysis of remaining 7 tasks). 456



**Figure 4. Consolidated homological distances between fMRI tasks and rest.** The left and right panel represents the distance between tasks in zeroth (**Panel A**) and first (**Panel B**) homology, calculated by Hausdorff distance and Wasserstein distance respectively. Each panel also contains three components, including the task-wise distance, the average distance, and the variance plot. Due to the small size of the consolidated graph, there was no second homology detected in the corresponding topological space.

### 3.4.1. Resting state analysis

Fixing the task and extracting functional networks enabled the characterization of 458 within-brain connectivity and the identification of unique topological patterns in functional 459 networks. Particularly, the default mode is present in the pair with the largest Wasserstein 460 distance in H0, H1, and H2 homology, and it also has the largest average Wasserstein 461 distance in H1 and H2 analysis (see Figure 5), suggesting a significant level of functional 462 specialization within the default mode during resting state. Extensive studies and literature 463 have validated that the default mode is more active and involved in introspective processes 464 and is typically deactivated in the engagement of goal-oriented tasks, which is referred 465 to as the "resting state dichotomy" of default mode network [57–59]. This finding further 466 reassured the robustness of the capability of the topological system to detect unique features 467 in certain activities. 468

In addition, we also discovered that the limbic system has the highest average Wasser-469 stein distance in the zeroth homology, indicating that it is the most distinct functional 470 network when we compare the pattern of connected components between functional net-471 works [15,60] (see Figure 5A). The limbic system is known for its role in memory- and 472 emotion-related activities [61–63], and the distinct connectivity pattern discovered reveals 473 that there might still be some memory or emotional processing even during the resting state. 474 Furthermore, the results can also serve as an indication of the individual heterogeneity 475 in their resting state behavior which may involve slight mind activities. The high level of 476 differentiation in H0 task pair with the limbic system is also reconfirmed in the mesoscopic 477 level analysis in emotional task and working memory task (see Figure ??A and ??A) 478



**Figure 5. Group-Average homological distances between brain circuits (FNs) at rest (e.g. Resting State Networks).** Three panels are positioned similarly to previous figures where they represent the distance of zeroth homology (**Panel A**), first homology (**Panel B**), and second homology (**Panel C**) between pairs of FNs. Group-average FNs are extracted based on Yeo's parcellation. The zeroth homological distance is computed using the Hausdorff formula while the first and second homology distance are computed using the Wasserstein formula. Each panel contains the triangular distance heatmap, the average distance bar plot, and the variance circular plots among functional networks.

#### 3.5. Individual subject analysis

While the group-average level connectomes (global level, consolidated level, and 480 mesoscopic level) provide topological insights in a collective pattern, transitioning to the 481 individual level could further offer a more personalized perspective with after-persistent-482 homology group insights. Moving beyond the aggregation of group data, individual-level 483 analysis would also allow the consideration of inter-individual variability and consistency 484 across different scales to bring even more robustness to the experimental design. Similar to 485 the previous setting, we investigated the individual global level with consensus voting as 486 well as the individual mesoscopic level with Kullback-Leibler divergence (KL divergence) 487 respectively [64]. 488

# 3.5.1. Macroscopic whole-brain level

With 100 unrelated subjects from the HCP database, the individual macroscopic level analysis contains 100 independent persistent homology with pair-wise task distance. At the individual macroscopic analysis, we still used the Hausdorff distance for the zeroth homology and the Wasserstein distance for the first and second homology. We evaluated the most distinct pair of tasks in each individual and **Figure** 6 shows the number of times each pair of tasks appeared as the most differentiated task pair.

Particularly, the zeroth homology displayed the largest variability with the max count 496 of the task pair being the smallest among the three homology groups, thus resulting in 497 a more diffused pattern in the consensus voting heatmap (see Figure 6A). This serves as 498 another explanation for the impact of the choice of graph representation on the zeroth 499 homology analysis that it is relatively more varied. However, we also see the resting-motor 500 task pair as one of the task pairs that have a high frequency at the individual level H0 501 results. Furthermore, the first homology still demonstrates the consistency with the group-502 averaged macroscopic level as well as consolidated level analysis, where it not only has 503 the motor task-resting state as the most frequent task pair, but the max count is also the 504 highest, indicating the robustness of the first homology in identifying brain connectivity 505 pattern with different activities (see Figure 6B). The second homology also shows the motor 506 task-resting state pair as the most frequent task pair, which further validates our findings 507 shown above (see Figure 6C). The individual level analysis on the macroscopic level adds 508

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**Figure 6. Individual consensus heatmap between tasks at macroscopic level.** Distance matrices between functional networks in 100 unrelated subjects were collected, and for each pair of functional networks, the frequency of it appearing as the most distinct pair among 100 subjects was counted, resulting in a majority voting heatmap for 3 homology groups (**Panel A** is the zeroth homology, **Panel B** is the second homology, and **Panel C** is the third homology). The number in the voting matrix represents the number of times the corresponding pair revealed the highest distance in one subject, and all numbers in one heatmap triangle should sum up to 100 for 100 subjects.

another layer to the group-averaged level analysis, where either the variability in the zeroth homology or the consistency in the first and second homology both further agree with the interpretation from previous sections.

#### 3.5.2. All-to-REST, mesoscopic analysis

At the individual mesoscopic level, the amount of analysis increased dramatically, 513 with 100 individuals, 8 tasks, 8 functional networks, and 3 homological classes. In this 514 case, it is difficult to analyze the distance between homology groups as we did at the 515 group-averaged level. As validated in previous studies as well as our macroscopic level 516 analysis, the resting state analysis tends to be the most distinct task compared to other 517 tasks that include some activity engagement [15]. Therefore, we collected individual level 518 all-to-REST distance and compared them across the functional network dimension and task 519 dimension. 520

For the mesoscopic level in an all-to-REST setting, we picked three functional network 521 pairs that have the highest distance measure from the group-averaged results (section 522 3.4.1) for all three homology groups. For each pair of functional networks, we collected 14 523 vectors, with each FN having 7 vectors containing 100 individual level distance measures 524 between the 7 non-resting-state tasks and resting state task (see **Figure ??**), and then we compared the KL divergence between the two functional networks with vectors from the 526 same non-resting-state task (Figure 7). In other words, the KL divergence measures the 527 difference between two distributions (two functional networks respectively for all subjects) 528 of the distance measure between the non-resting-state task and resting-state task.

For zeroth homology, we find that the social task is more differentiated from the resting 530 state compared to others when we consider functional network pairs of dorsal attention and 531 subcortical, as well as visual network with the limbic system (see Figure 7, panel B, C). These 532 results take the consideration of both task activities and interactions between functional 533 networks at the same time, indicating that the selected pair of functional networks have 534 very different brain connectivity configurations in social tasks compared to the resting state. 535 The default mode is still involved in the most selected pair of functional networks in the 536 resting state, and the relational task has a very high KL divergence compared with the 537 resting state in many functional pairs for the first and second homology, including default 538 mode with limbic, subcortical, visual, dorsal and ventral attention (see Figure 7, panel D-I). 539

#### 3.5.3. All-to-REST, task analysis

The task analysis in an all-to-REST setting provided another perspective where the observation of functional network reconfiguration from resting state to other tasks is highlighted. In this case, we fixed the task that compared with the resting state and focused 543

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**Figure 7. KL divergence plot for top three functional networks pair in all-to-RESTING setting.** Rows represent homological groups (**Panel A-C** is the zeroth homology, **Panel D-F** is the first homology, and **Panel G-I** is the second homology) and each has three panels consisting of the top three most distinct pairs of functional networks inferred from the group-averaged mesoscopic analysis. The bar plot demonstrates the KL divergence between the selected pair of functional networks, in terms of the 100 individual-level distance between the resting state with other tasks.

on the KL divergence between all pairs of functional networks in the first phonological order (see **Figure** 8, see **Figure** ?? and **Figure** ?? for the zeroth and second homology). To demonstrate the reconfiguration from resting to other tasks, we selected the top five largest KL divergences for each task and ranked them by the line strength in the circular plot.

Some of the tasks displayed very unified patterns, such as the emotional task and 548 working memory task, where all the highest KL divergence included one functional network 549 (see Figure 8, emotional and working memory panel). The observation drawn from those 550 two tasks showed that the reconfiguration from resting state to emotional task actually 551 involves a lot of activities for somatomotor, and shifts to working memory task will require 552 the subcortical region to take the most response. The somatomotor network includes 553 most of the somatosensory area, which is closely related to emotional regulation, and 554 the subcortical region is known to be involved in complex activities such as memoryrelated activities. In addition, we also observed that the somatomotor network also has 556 the strongest link in the motor task, and the subcortical region is present as the dense 557

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**Figure 8.** KL divergence circular plot for 7 fMRI tasks-to-RESTING with functional network comparison in H1. Here we fixed the task which compared with the resting state and visualized the top five KL divergence between functional networks. The KL divergence is normalized with regards to the top five measures and demonstrated by the strength of circular connectivity.

connectivity hub in many task plots, which is an indication of the common underlying mechanism of brain circuit shifts from resting states to any other activities (see **Figure 8**, gambling, motor, relational, and social panel).

# 4. Discussion

At the heart of many complex systems resides a set of fine-tuned mesoscopic struc-562 tures whose roles have been linked with complex orchestrations of emergent phenomena. 563 Understanding complex higher-order behaviors arisen at a scale between the microscopic 564 (brain regions) and macroscopic (whole-brain) level would set the stage to a more compre-565 hensive understanding of the human brain large-scale functional circuitry. There are two 566 kinds of mesoscopic structures: i) local/quasilocal (e.g., ground-truth communities) and 567 ii) non-local such as topological strata of complex networks. In this work, we proposed 568 a TDA formalism to disentangle the higher-order properties of brain sub-circuits (FNs) 569 among different fMRI tasks. The major contributions of our framework on higher-order 570 brain systems over other existing ones [39,65,66] are that i) this framework allows the study 571 of non-localized properties of an *a priori* set of localized/quasilocalized sub-networks, *ii*) 572 through this innovative mesoscopic kernel proposal, we observed various results that 573 align well with the current knowledge in network neuroscience and also highlighted the resting-state dichotomy of default mode network as well as the role of the limbic system 575 in the process of functional (re)configuration, iii) we included not only within-task and 576 within-FN scenarios, but also investigated the bi-level analysis that considered both task 577 and FN levels at the same time. The construction of fMRI brain connectivity and Yeo's ROI-578 to-FN mappings enabled multi-level homological group calculation and corresponding 579 graph-based analysis. With 7 different tasks in addition to resting state, previous studies 580 found that the brain functional reconfiguration in macroscopic (global-level) is hard to 581 observe, while different tasks will rather trigger more shifts in mesoscopic structure (brain 582 functional networks level) [13,67,68]. Hence, we organized our framework in 5 settings: 583 a) group-averaged global level, b) group-averaged consolidated level, c) group-averaged 584 mesoscopic level, d) individual global level, and e) individual all-to-REST level with func-585 tional network analysis and task analysis. At the first three levels, we conducted the topological data analysis at the group-representative level, which gives a broader view 587 of the between-task, between rest-task and between-FN distance. When we look at the 688 individual level (each subject's FCs), we took a different approach from other existing brain 589 connectivity fingerprint frameworks [13,69]. Specifically, in the first step, we computed the 590 distance measures on an individual basis by using the KL divergence to compare the distri-591 bution of individual-level distance. In the second step, we used consensus analysis to infer 592 group-level behavior, as opposed to using simple average. Through this setting, we found 593 that three homological groups provided complementary insights in both task and subject 594 domain. More specifically, the zeroth homology measures the connected components; 595 the first homology measures the 2-dimensional hole encapsulated by one-dimensional 596 functional edges; the second homology measures the 3-dimensional cavities encapsulated 597 by 2-dimensional triangles. These homological groups and their algebraic structures are 598 hypothesized in our paper to characterize topological spaces parameterized by the brain connectivity network. 600

Noticeably in work led by Fox and colleagues [70], the authors suggested that emotion 601 task might be regulated by reduced functional activity attenuated by self-referential aspects 602 of such task. In general, "harder" tasks (i.e., relational) require an increasing level of global integration which should reflect through a relatively small number of connected 604 components (smaller Betti number 0). It is worthy to note that the motor cortex was identified as the hubs of broadcasting transduction [15] which contains brain regions that 606 are critical to broadcasting information to other regions of the brain. Compared to the resting state - the absence of cognitive requirement from fMRI tasks, motor task, which 608 employs motor cortex brain regions, modulates global integrative cooperation among 609 brain regions by forming first-order cycles across FNs. Combining both zeroth (connected 610 components) and first homological (graph-theoretical cycles) distance results, we see that 611 there exists a cognitive "switch" taking place at a global level to form connectivities that 612 results in *i*) less number of connected components and *ii*) more globally integrated FNs as 613 reflected by first-order cycles. 614

By consolidating the global view of the group-averaged connectome, we found that 615 the H1 homology displayed stable topological invariants with its consistency in the most 616 distinct pair of tasks as well as pertaining to a clear block diagonal structure on the distance 617 heatmap. Both global and consolidated views displayed significant signals that the resting 618 state and motor task are the most different task pairs [55,56], while they are also the first and 619 second distinct tasks in terms of the average distance (see Figure 4B,C). In this case, a simple observation we can draw from the analysis is that the brain takes some reconfiguration from 621 resting state to other non-motor tasks, and then it requires further shifts in connectivity to get to the motor task. In addition, we further studied the individual-level homological 623 scaffolds and performed group-level consensus voting on the most differentiated pair of tasks over 100 unrelated subjects (see Figure 6B,C). The H1 and H2 majority voting results 625 again showed that the motor task is the most apart task from the resting state, and H1 626 also has the highest frequency count on the largest count among all three homological 627 groups, indicating that it has the most consistent and robust capability to understand the 628 homological scaffold in brain connectivity topological space.

Noticeably, the strong topological invariant of the H1 homology between the macro-630 scopic (whole-brain) level with consolidated (super-graph) level demonstrated the existence 631 of self-similarity property unravelled by the higher-order properties of brain functional sub-632 circuit [71–73]. Regarding the macroscopic level of the brain connectome as the "zoomed-in" representation of the consolidated graph, the overall pattern of the Wasserstein distance 634 between tasks still holds. While both the macroscopic level and consolidated level have 635 the resting-state task and motor task pair as the most differentiated task pair, further ob-636 servation was found by looking at the row in the distance heatmap that involves resting 637 state task and motor task all have high Wasserstein distance, together forming a block 638 pattern that separates resting state task as well as motor task from the other tasks. This 639

phenomenon guarantees the "scale-free" property of the first homological group on the complex brain system and provides a consistent potential for this topological framework for other higher-order complex network systems [71,73].

We partitioned the brain connectome with the 7 Yeo functional network as well as a 643 subcortical structure, resulting in 8 separate sub-networks. Since the resting state brain connectivity structure is the closest to Yeo's partition, the first assessment that we did at the 645 mesoscopic level was to fix the resting state task and compare the distance between two 646 functional networks. The mesoscopic level analysis captured the "functional dichotomy" 647 in the resting state by both the most differentiated task pairs as well as the highest average 648 distance (see **Figure** 5B,C), where default mode is the most dominant network [13,70,74]. 649 The brain network studies typically focus on either the within-task configuration or within-650 network configuration [14,15,65,75,76], the individual-level functional network partition 651 further revealed patterns in the brain that are shifted between resting state to other tasks as 652 well as between two functional networks. The individual all-to-rest mesoscopic analysis considered both task and functional network "switches". Such bi-level perspective allows 654 the investigation of the most distinct functional network pairs in resting state on their 655 reconfiguration from resting state to other tasks (see **Figure** 7). While maintaining the 656 bi-level design of the experiments, we flipped the two-level in the all-to-rest task analysis to investigate, from resting state to each task, how pairs of functional network are shifted 658 (see Figure 8). The unique patterns in the top 5 pairs of functional networks also enabled 659 hub identification in the process of the task switch, and closer tasks also displayed similar 660 patterns, indicating that they underwent similar reconfiguration from the resting state.

This study has certain limitations. In the consolidation process from the global-level 662 graph, we specifically opted for max normalization to construct the super graph. Since 663 altering the normalization method may potentially modify the inter-connectivity of func-664 tional networks, future research could investigate different normalization techniques. For instance, using average connectivity to define the consolidated graph might impact not only 666 the topological structure of the super graph but also its self-similarity properties from the 667 homological kernels. Moreover, not only does the choice of the homological group influence 668 the distance measure between tasks or functional networks, but the graph itself also plays a crucial role. Our experiments were solely conducted on the Glasser parcellation with 374 670 nodes (360 cortical regions + 14 sub-cortical regions). Exploring alternative parcellations in 671 both brain cortical and subcortical regions ([28,77]) and incorporating multiple parcellation 672 scales could offer additional insights into mesoscopic cognitive reconfiguration and its 673 scaling-related properties.

In summary, we presented a novel framework that uses persistent homology to 675 characterize brain connectivity in the topological space. Based on the nature of each homological group, we selected different distance measures correspondingly. The zeroth 677 persistent homology is all born at 0 so the Wasserstein distance is not a good fit, but the Haursdorff distance is more appropriate for measuring the 1D distribution of the 679 point cloud. However, the first and second homology are closer to the diagonal in the 680 persistent homology diagram, and thus the Wasserstein distance with partial mapping 681 which serves as a simulation of moving one distribution to another in a geodesic setting 682 would become better in this case. We validated that the first homology gives very consistent 683 and topological invariant findings in different levels of analysis, which offers a scaling 684 invariant perspective, and we find that the framework is capable of capturing signals that 685 are well-studied in the literature, but also discovered some unique patterns in the brain circuit triggering diverse processes among different fMRI tasks and resting conditions. From a wider perspective, our formalism can be applied, beyond brain connectomics, to 688 study non-localized coordination patterns induced by localized, pre-defined structures 689 stretching across different complex network fibers. 600

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DMN

SUBC

KL divergence

FP

Limbic

Frontopatietal

Default Mode Network

Kullback–Leibler divergence

Sub-cortical regions

	Xuan Wang, Sum Bao: Visualizatio Data curation; W draft: Project Sui	ita Garai, Fredericks Xu, Alan D. Kaplan, Yize Zhao: Writing original draft. Jingxuan n. Giovanni Petri: Methodology; Writing original draft. Enrico Amico, Joaquin Goñi: /riting original draft. Li Shen: Conceptualization; Formal analysis; Writing original pervision: Funding acquisition.	694 695 696 697
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	Conflicts of Interest: Authors declare no conflict of interest.		706
	<b>Abbreviations</b> The following at	breviations are used in this manuscript:	707 708
	TDA FC FN VIS SM	Topological data analysis Functional Connectomes Functional Network Visual SomatoMotor	709
	DA VA	Ventral attention	710

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